## Controls

Solid-State Switching Devices
Reference Manual • April 2009


## Low-Voltage Controls and Distribution

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## Controls - Solid-State Switching Devices

## Introduction

## Overview



# Solid-State Switching Devices 

## General data

## Overview



SIRIUS 3RF2 solid-state switching devices
The 3RF solid-state switching devices reliably switch a wide range of different loads with alternating voltages in 50 and 60 Hz systems.
Solid-state switching devices for resistive loads

- Solid-state relays
- Solid-state contactors
- Function modules

Solid-state switching devices for switching motors

- Solid-state contactors
- Solid-state reversing contactors


## SIRIUS 3RF2 - for almost unending activity

Conventional electromechanical controlgear is often overtaxed by the rise in the number of switching operations. A high switching frequency results in frequent failure and short replacement cycles. However, this does not have to be the case, because with the latest generation of our SIRIUS 3RF2 solid-state switching devices we provide you with solid-state relays and contactors with a particularly long endurance - for almost unending activity even under the toughest conditions and under high mechanical load, but also in noise-sensitive areas.

## Proved time and again in service

SIRIUS 3RF2 solid-state switching devices have firmly established in industrial applications. They are used above all in applications where loads are switched frequently - mainly with resistive load controllers, with the control of electrical heat or the control of valves and motors in conveyor systems. In addition to its use in areas with high switching frequencies, their silent switching means that SIRIUS is also ideally suited for use in noisesensitive areas, such as offices or hospitals.

## The most reliable solution for any application

Compared to mechanical controlgear, our SIRIUS 3RF2 solidstate switching devices stand out due to their considerably longer service life. Thanks to the high product quality, their switching is extremely precise, reliable and, above all, insusceptible to faults. With its variable connection methods and a wide spread of control voltages, the SIRIUS 3RF2 family is universally applicable. Depending on the individual requirements of the application, our modular controlgear can also be quite easily expanded by the addition of standardized function modules.

## Also for switching motors

In order to achieve higher productivity, the switching frequency is continuously increased. It is no problem for our SIRIUS solidstate contactors to switch motors. With induction motors up to 7.5 kW , they can reliably withstand even the highest switching frequencies. Even a continuous change in the direction of rotation is possible with the solid-state reversing contactors. Both versions can be perfectly combined with components from the SIRIUS modular system. Connecting with SIRIUS motor starter protectors or SIRIUS overload relay can be implemented without any further steps.

## Always on the sunny side with SIRIUS

Because SIRIUS 3RF2 offers even more:

- The space-saving and compact side-by-side mounting ensures reliable operation up to an ambient temperature of $+60^{\circ} \mathrm{C}$.
- Thanks to fast configuration and the ease of mounting and start-up, you save not only time but also expenses.


## Connection methods

The devices are available with screw terminals (box terminals), spring-type terminals or ring terminal lugs.

## (c) Screw terminals

O Spring-type terminals

## (1) Ring terminal lug connections

These connections are indicated in the Technical specifications by orange backgrounds.

## Solid-State Switching Devices for Resistive Loads

## General data

## Overview

| Type | Solid-state relays Single-phase |  |  | Solid-state contactors |  | Function modules |  |  | Heating current monitoring | Power controllers | Power regulators |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Three- | Single- | Three- | Converters |  | ring |  |  |  |
|  | 22.5 mm | 45 mm | 45 mm |  |  |  | Basic | Extended |  |  |  |
| Usage |  |  |  |  |  |  |  |  |  |  |  |
| Simple use of existing solid-state relays | $\square$ | $\checkmark$ | $\square$ | $\square$ | $\square$ | -- | -- | -- | -- | -- | -- |
| Complete unit "Ready to use" | $\square$ | $\square$ | $\square$ | $\checkmark$ | $\checkmark$ | -- | -- | -- | -- | -- | -- |
| Space-saving | $\checkmark$ | -- | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | -- | -- | -- | -- |
| Can be extended with modular function modules | $\checkmark$ | -- | 1) | $\checkmark$ | 1) | -- | -- | -- | -- | -- | -- |
| Frequent switching and monitoring of loads and solid-state relays/solid-state contactors | -- | -- | -- | -- | -- | -- | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| Monitoring of up to 6 partial loads | -- | -- | -- | -- | -- | -- | $\checkmark$ | -- | $\checkmark$ | $\checkmark$ | -- |
| Monitoring of more than 6 partial loads | -- | -- | -- | -- | -- | -- | -- | $\checkmark$ | -- | -- | -- |
| Control of the heating power through an analog input | -- | -- | -- | -- | -- | $\checkmark$ | -- | -- | -- | $\checkmark$ | $\checkmark$ |
| Power control | -- | -- | -- | -- | -- | -- | -- | - | -- | -- | $\checkmark$ |
| Startup |  |  |  |  |  |  |  |  |  |  |  |
| Easy setting of setpoint values with "Teach" button | -- | -- | -- | -- | -- | -- | $\checkmark$ | $\checkmark$ | -- | $\checkmark$ | $\checkmark$ |
| "Remote Teach" input for setting setpoints | -- | -- | -- | -- | -- | -- | -- | -- | $\checkmark$ | -- | -- |
| Mounting |  |  |  |  |  |  |  |  |  |  |  |
| Mounting onto mounting rails or mounting plates | -- | -- | -- | $\checkmark$ | $\checkmark$ | -- | -- | -- | -- | -- | -- |
| Can be snapped directly onto a solid-state relay or contactor | -- | -- | -- | -- | -- | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| For use with "Coolplate" heat sink | $\checkmark$ | $\checkmark$ | $\checkmark$ | -- | -- | -- | -- | -- | -- | -- | -- |
| Cable routing |  |  |  |  |  |  |  |  |  |  |  |
| Connection of load circuit as for controlgear | $\checkmark$ | -- | $\checkmark$ | $\checkmark$ | $\checkmark$ | -- | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| Connection of load circuit from above | -- | $\checkmark$ | -- | -- | -- | -- | -- | -- | -- | -- | -- |
| $\checkmark$ Function is available |  |  |  |  |  |  |  |  |  |  |  |
| $\square$ Function is possible |  |  |  |  |  |  |  |  |  |  |  |

## General data

## Design

There is no typical design of a load feeder with solid-state relays or solid-state contactors; instead, the great variety of connection methods and control voltages offers universal application opportunities. SIRIUS solid-state relays and solid-state contactors can be installed in fuseless or fused feeders, as required. There are special versions with which it is even possible to achieve shortcircuit strength in a fuseless design.

## Connection methods

All SIRIUS solid-state switching devices are characterized by the great variance of connection methods. You can choose between the following connection methods:

## Screw connection

The screw connection system is the standard among industrial controls. Open terminals and a plus-minus screw are just two
features of this technology. Two conductors of up to $6 \mathrm{~mm}^{2}$ can be connected in just one terminal. As a result, loads of up to 50 A can be connected.

## Spring-type terminal connection system

This innovative technology manages without any screw connection. This means that very high vibration resistance is achieved. Two conductors of up to $2.5 \mathrm{~mm}^{2}$ can be connected to each terminal. As a result, loads of up to 20 A can be dealt with.

## Ring terminal lug connection

The ring terminal lug connection is equipped with an M5 screw. Ring terminal lugs of up to $25 \mathrm{~mm}^{2}$ can be connected. In this way it is possible to connect even high powers with current strengths of up to 90 A safely. Finger-safety is provided in this case too with a special cover.

## Function

## Switching functions

In order to guarantee an optimized control method for different loads, the functionality of our solid-state switching devices can be adapted accordingly.
The "zero-point switching" method has proved to be ideal for resistive loads, i. e. where the power semiconductor is activated at zero voltage.
For inductive loads, on the other hand, for example in the case of valves, it is better to go with "instantaneous switching". By distributing the ON point over the entire sine curve of the mains voltage, disturbances are reduced to a minimum.

## Performance characteristics

The performance of the solid-state switching devices is substantially determined by the type of power semiconductors used and the internal design. In the case of the SIRIUS solid-state contactors and solid-state relays, only thyristors are used in place of less powerful Triacs.
Two of the most important features of thyristors are the blocking voltage and the maximum load integral:

## Blocking voltage

Thyristors with a high blocking voltage can also be operated without difficulty in networks with high interference voltages. Separate protective measures, such as a protective circuit with a varistor, are not necessary in most cases.
For example, thyristors with 800 V blocking voltage are fitted in the devices for operation in networks up to 230 V . Thyristors with up to 1600 V are used for power systems with higher voltages.

## Maximum load integral

One of the purposes of specifying the maximum load integral $(R t)$ is to determine the rating of the short-circuit protection. Only a large power semiconductor with a correspondingly high $\mathrm{P} t$ value can be given appropriate protection against destruction from a short-circuit by means of a protective device matched to the application. However, the devices are also characterized by the optimum matching of the thyristors ( $R t$ value) with the rated currents. The rated currents specified on the devices according to EN 60947-4-3 were confirmed by extensive testing.
You can find more information on the Internet at:
htto://WWW.siemens.com/cd/is_schalten/html 76/schalt.htm

## Integration

## Notes on integration in the load feeders

The SIRIUS solid-state switching devices are very easy to integrate into the load feeders thanks to their industrial connection method and design.
Particular attention must however be paid to the circumstances of the installation and ambient conditions, as the performance of the solid-state switching devices is largely dependent on these. Depending on the version, certain restrictions must be observed. Detailed information, for example in relation to solid-state contactors about the minimum spacing and to solid-state relays about the choice of heat sink, is given in the technical specifications and the product data sheets.
Despite the rugged power semiconductors that are used, solidstate switching devices respond more sensitively to short-circuits in the load feeder. Consequently, special precautions have to be taken against destruction, depending on the type of design.
Siemens generally recommends using SITOR semiconductor protection fuses. These fuses also provide protection against destruction in the event of a short-circuit even when the solidstate contactors and solid-state relays are fully utilized.
Alternatively, if there is lower loading, protection can also be provided by standard fuses or miniature circuit breakers. This protection is achieved by overdimensioning the solid-state switching devices accordingly. The technical specifications and the product data sheets contain details both about the solid-state fuse protection itself and about use of the devices with conventional protection equipment.
The solid-state switching devices for resistive loads are suitable for interference-free operation in industrial networks without further measures. If they are used in public networks, it may be necessary for conducted interference to be reduced by means of filters. This does not include the special solid-state contactors of type 3RF23..-.CA.. "Low Noise". These comply with the class $B$ limit values up to a rated current of 16 A. If other versions are used, and at currents of over 16 A, standard filters can be used in order to comply with the limit values. The decisive factors when it comes to selecting the filters are essentially the current loading and the other parameters (operational voltage, design type, etc.) in the load feeder.
Suitable filters can be ordered from EPCOS AG.
You can find more information on the Internet at:
http://www.epcos.com

## Overview

## Solid-state relays

SIRIUS solid-state relays are suitable for surface mounting on existing cooling surfaces. Mounting is quick and easy, involving just two screws. The special technology of the power semiconductor ensures there is excellent thermal contact with the heat sink. Depending on the nature of the cooler, the capacity reaches up to 88 A on resistive loads.
The solid-state relays are available in three different versions:

- 3RF21 single-phase solid-state relays with a width of 22.5 mm
- 3RF20 single-phase solid-state relays with a width of 45 mm
- 3RF22 three-phase solid-state relays with a width of 45 mm .

The 3RF21 and 3RF22 solid-state relays can be expanded with various function modules to adapt them to individual applications.

## Version for resistive loads, "zero-point switching"

This standard version is often used for switching space heaters on and off.

## Version for inductive loads, "instantaneous switching"

In this version the solid-state relay is specifically matched to inductive loads. Whether it is a matter of frequent actuation of the valves in a filling plant or starting and stopping small operating mechanisms in packet distribution systems, operation is carried out safely and noiselessly.

## Single-phase solid-state relay with a width of 22.5 mm

With its compact design, which stays the same even at currents of up to 88 A, the 3RF21 solid-state relay is the ultimate in spacesaving construction, at a width of 22.5 mm . The logical connection method, with the power infeed from above and load connection from below, ensures tidy installation in the control cabinet.

## Single-phase solid-state relay with a width of 45 mm

The solid-state relays with a width of 45 mm provide for connection of the power supply lead and the load from above. This makes it easy to replace existing solid-state relays in existing arrangements. The connection of the control cable also saves space in much the same way as the 22.5 mm design, as it is simply plugged on.
Three-phase solid-state relay with a width of 45 mm
With its compact design, which stays the same even at currents of up to 55 A, the 3RF22 solid-state relay is the ultimate in spacesaving construction, at a width of 45 mm . The logical connection method, with the power infeed from above and load connection from below, ensures tidy installation in the control cabinet.
The three-phase solid-state relays are available with

- two-phase control and
- three-phase control.


## Function

Three-phase solid-state switching devices
Two-phase controlled version
A three-phase control system is not required for many threephase current applications. Loads in a delta circuit or star circuit which have no connection to the neutral conductor can also be safely switched on and off using just two phases.
Nevertheless, the three-phase 3RF22 and 3RF24 solid-state switching devices permit all three phases to be connected to the switching device, in which case the middle phase is looped directly through the device. Compared to a three-phase controlled device, the lower power loss allows more compact installations.
Three-phase controlled version
This version is used for three-phase current applications in which the system requires all phases to be switched on and off, or for loads in a star circuit with connection to the neutral conductor.

## Configuration

## Selecting solid-state relays

When selecting solid-state relays, in addition to information about the network, the load and the ambient conditions it is also necessary to know details of the planned design. The solid-state relays can only conform to their specific technical specifications if they are mounted with appropriate care on an adequately dimensioned heat sink.
The following procedure is recommended:

- Determine the rated current of the load and the mains voltage
- Select the relay design and choose a solid-state relay with higher rated current than the load
- Determine the thermal resistance of the proposed heat sink
- Check the correct relay size with the aid of the diagrams

You can find more information on the Internet at:
http://www.siemens.com/cd/is_schalten/html_76/schalt.htm

## Solid-State Switching Devices for Resistive Loads

Solid-State Relays
3RF21 solid-state relays, single-phase, 22.5 mm

## Overview

## 22.5 mm solid-state relays

With its compact design, which stays the same even at currents of up to 88 A, the 3RF21 solid-state relay is the ultimate in spacesaving construction, at a width of 22.5 mm . The logical connection method, with the power infeed from above and load connection from below, ensures tidy installation in the control cabinet.

Technical specifications

| Type |  | 3RF21 ..-1.... | 3RF21 ..-2.... | 3RF21 ..-3.... |
| :---: | :---: | :---: | :---: | :---: |
| General data |  |  |  |  |
| Ambient temperature <br> - During operation, derating from $40^{\circ} \mathrm{C}$ <br> - During storage | $\begin{aligned} & { }^{\circ} \mathrm{C} \\ & { }^{\circ} \mathrm{C} \end{aligned}$ | $\begin{aligned} & -25 \ldots+60 \\ & -55 \ldots+80 \end{aligned}$ |  |  |
| Installation altitude | m | $0 \ldots$ 1000; derating from 1000 |  |  |
| Shock resistance acc. to IEC 60068-2-27 | $\mathrm{g} / \mathrm{ms}$ | 15/11 |  |  |
| Vibration resistance acc. to IEC 60068-2-6 | $g$ | 2 |  |  |
| Degree of protection |  | IP20 |  |  |
| Electromagnetic compatibility (EMC) <br> - Emitted interference <br> - Conducted interference voltage acc. to IEC 60947-4-3 <br> - Emitted, high-frequency interference voltage acc. to IEC 60947-4-3 |  | Class A for industrial applications <br> Class A for industrial applications |  |  |
| - Interference immunity <br> - Electrostatic discharge acc. to IEC 61000-4-2 (corresponds to degree of severity 3 ) <br> - Induced RF fields acc. to IEC 61000-4-6 <br> - Burst acc. to IEC 61000-4-4 <br> - Surge acc. to IEC 61000-4-5 | kV <br> MHz <br> kV <br> kV | Contact discharge 4; air discharg <br> 0.15 ... 80; $140 \mathrm{~dB} \mu \mathrm{~V}$; behavior c <br> 2/5.0 kHz; behavior criterion 1 Conductor - ground 2; conductor | 8; behavior criterion 2 <br> rion 1 <br> conductor 1; behavior criterion |  |
| Connection type |  | ()) Screw terminals | OO Spring-type terminals | Ring terminal lug connections |
| Connection, main contacts |  |  |  |  |
| - Conductor cross-section <br> - Solid <br> - Finely stranded with end sleeve <br> - Finely stranded without end sleeve <br> - Solid or stranded, AWG cables <br> - Terminal screw <br> - Tightening torque <br> - Cable lug <br> - DIN <br> - JIS | $\mathrm{mm}^{2}$ <br> $\mathrm{mm}^{2}$ <br> $\mathrm{mm}^{2}$ <br> Nm <br> lb.in | $\begin{aligned} & \left.2 \times(1.5 \ldots 2.5)^{1)}, 2 \times(2.5 \ldots 6)^{1}\right) \\ & 2 \times(1 \ldots 2.5)^{1}, 2 \times(2.5 \ldots 6)^{1}, \\ & 1 \times 10 \\ & - \\ & 2 \times(\text { AWG } 14 \ldots 10) \\ & \text { M4 } \\ & 2 \ldots 2.5 \\ & 7 \ldots 10.3 \end{aligned}$ | $\left.\begin{array}{l} 2 \times\left(\begin{array}{lll} 0.5 & \ldots & 2.5) \\ 2 \times(0.5 \ldots & 1.5 \end{array}\right) \\ 2 \times(0.5 \ldots \end{array}\right)$ -- $-$ $--$ | $\begin{aligned} & \text {-- } \\ & -- \\ & -- \\ & -- \\ & \text { M5 } \\ & 2.5 \ldots .2 \\ & 10.3 \ldots 7 \end{aligned}$ <br> DIN 46234-5-2.5, -5-6, -5-10, <br> -5-16, -5-25 <br> JIS C 2805 R 2-5, 5.5-5, 8-5, 14-5 |
| Connection, auxiliary/control contacts |  |  |  |  |
| - Conductor cross-section | $\begin{aligned} & \mathrm{mm} \\ & \text { AWG } \end{aligned}$ | $\begin{aligned} & 1 \times(0.5 \ldots 2.5), 2 \times(0.5 \ldots 1.0) \\ & 20 \ldots 12 \end{aligned}$ | $\begin{aligned} & 0.5 \ldots 2.5 \\ & 20 \ldots 12 \end{aligned}$ | $\begin{aligned} & 1 \times(0.5 \ldots 2.5), 2 \times(0.5 \ldots 1.0) \\ & 20 \ldots 12 \end{aligned}$ |
| - Stripped length | mm | 7 | 10 | 7 |
| - Terminal screw |  | M3 | -- | M3 |
| - Tightening torque | Nm lb .in | $\begin{aligned} & 0.5 \ldots 0.6 \\ & 4.5 \ldots 5.3 \end{aligned}$ | -- | $\begin{array}{ll} 0.5 & \ldots .6 \\ 4.5 & \ldots \\ 5.3 \end{array}$ |

1) If two different conductor cross-sections are connected to one clamping point, both cross-sections must lie in the range specified. If identical cross-sections are used, this restriction does not apply.

## Solid-State Switching Devices for Resistive Loads

Solid-State Relays

## 3RF21 solid-state relays, single-phase, 22.5 mm

| Order No. | $\begin{aligned} & \boldsymbol{I}_{\max }{ }^{\mathbf{1})} \\ & \text { at } R_{\text {thha }} / T_{\mathrm{u}}=40^{\circ} \mathrm{C} \end{aligned}$ |  | $I_{\mathrm{e}}$ acc. to IEC 60947-4-3 at $\mathrm{R}_{\text {thha }} / \mathrm{T}_{\mathrm{u}}=40^{\circ} \mathrm{C}$ |  | $I_{\mathrm{e}}$ acc. to UL/CSA at $R_{\text {thha }} / T_{u}=50^{\circ} \mathrm{C}$ |  | Power loss at $I_{\text {max }}$ | Minimum load current | Leakage current |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | A | K/W | A | K/W | A | K/W | W | A | mA |
| Main circuit |  |  |  |  |  |  |  |  |  |
| 3RF21 20-..... | 20 | 2.0 | 20 | 1.7 | 20 | 1.3 | 28.6 | 0.1 | 10 |
| 3RF21 30-1.... | 30 | 1.1 | 30 | 0.79 | 30 | 0.56 | 44.2 | 0.5 | 10 |
| 3RF21 50-1.... | 50 | 0.68 | 50 | 0.48 | 50 | 0.33 | 66 | 0.5 | 10 |
| 3RF21 50-2.... | 50 | 0.68 | 20 | 2.6 | 20 | 2.9 | 66 | 0.5 | 10 |
| 3RF21 50-3.... | 50 | 0.68 | 50 | 0.48 | 50 | 0.33 | 66 | 0.5 | 10 |
| 3RF21 70-1.... | 70 | 0.40 | 50 | 0.77 | 50 | 0.6 | 94 | 0.5 | 10 |
| 3RF21 90-1... | 88 | 0.33 | 50 | 0.94 | 50 | 0.85 | 118 | 0.5 | 10 |
| 3RF21 90-2.... | 88 | 0.33 | 20 | 2.8 | 20 | 3.5 | 118 | 0.5 | 10 |
| 3RF21 90-3.... | 88 | 0.33 | 88 | 0.22 | 83 | 0.19 | 118 | 0.5 | 10 |

1) $I_{\text {max }}$ provides information about the performance of the solid-state relay The actual permitted rated operational current $I_{\mathrm{e}}$ can be smaller depending on the connection method and cooling conditions.

Note: The required heat sinks for the corresponding load currents can be determined from the characteristic curves, page 12. The minimum thickness values for the mounting surface must be observed.

| Order No. | Rated impulse withstand capacity $\boldsymbol{I}_{\text {tsm }}$ | $\boldsymbol{I}^{\mathbf{2} \boldsymbol{t} \text { value }}$ |
| :--- | :--- | :--- |
|  | A | $\mathrm{A}^{2} \mathrm{~s}$ |
| Main circuit |  |  |
| 3RF21 20-..... | 200 | 200 |
| 3RF21 30-..A.2 | 300 | 450 |
| 3RF21 30-..A.4 | 300 | 450 |
| 3RF21 30-..A.5 | 300 | 450 |
| 3RF21 30-..A.6 | 400 | 800 |
| 3RF21 50-.... | 600 | 1800 |
| 3RF21 70-..A.2 | 1200 | 7200 |
| 3RF21 70-..A.4 | 1200 | 7200 |
| 3RF21 70-..A.5 | 1200 | 7200 |
| 3RF21 70-..A.6 | 1150 | 6600 |
| 3RF21 90-.... | 1150 | 6600 |


| Type |  | 3RF21 ..-.... 2 | 3RF21 ..-.... 4 | 3RF21 ..-... 5 | 3RF21 ..-.... 6 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Main circuit |  |  |  |  |  |
| Rated operational voltage $\boldsymbol{U}_{\mathbf{e}}$ | V | $24 . .230$ | 48 ... 460 | $48 . . .600$ | $48 \ldots 600$ |
| - Operating range | V | 20 ... 253 | 40 ... 506 | 40 ... 660 | 40 ... 660 |
| - Rated frequency | Hz | $50 / 60 \pm 10$ \% |  |  |  |
| Rated insulation voltage $\boldsymbol{U}_{\mathbf{i}}$ | V | 600 |  |  |  |
| Blocking voltage | V | 800 | 1200 |  | 1600 |
| Rage of voltage rise | $\mathrm{V} / \mathrm{\mu}$ | 1000 |  |  |  |


| Type |  | 3RF21 ..-... 0. | 3RF21 ..-... 1. |  | 3RF21 ..-...2. | 3RF21 ..-...4. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Control circuit |  |  |  |  |  |  |
| Method of operation |  | DC operation | AC/DC operation |  | AC operation | DC operation |
| Rated control supply voltage $\boldsymbol{U}_{\text {s }}$ | V | $\begin{aligned} & 24 \text { acc. to } \\ & \text { EN } 61131-2 \\ & \hline \end{aligned}$ | 24 AC | 24 DC | 110 ... 230 | $4 \ldots 30$ |
| Rated frequency of the control supply voltage | Hz | -- | $\begin{aligned} & 50 / 60 \\ & \pm 10 \% \end{aligned}$ | -- | 50/60 $\pm 10$ \% | -- |
| Control supply voltage, max. | V | 30 | 26.5 AC | 30 DC | 253 | 30 |
| Typical actuating current | mA | 20 / Low Power: 6.51) | 20 | 20 | 15 | 20 |
| Response voltage | V | 15 | 14 AC | 15 DC | 90 | 4 |
| Drop-out voltage | V | 5 | 5 AC | 5 DC | 40 | 1 |
| Operating times |  |  |  |  |  |  |
| - ON-delay | ms | 1 + max. one half-wave ${ }^{2)}$ | $10+\max$ half-wave |  | $40+\text { max. one }$ half-wave ${ }^{\text {) }}$ | 1 + max. one half-wave ${ }^{2)}$ |
| - OFF-delay | ms | 1 + max. one half-wave | $\begin{aligned} & 15+\text { max } \\ & \text { half-wave } \end{aligned}$ |  | 40 + max. one half-wave | 1 + max. one half-wave |

[^0]2) Only for zero-point-switching devices.

# Solid-State Switching Devices for Resistive Loads <br> Solid-State Relays 

3RF21 solid-state relays, single-phase, 22.5 mm
Fused version with semiconductor protection (similar to type of coordination "2")1)

The semiconductor protection for the SIRIUS controls can be used with different protective devices. This allows protection by means of LV HRC fuses of gG operational class or miniature circuit breakers. Siemens recommends the use of special SITOR semiconductor fuses. The table below lists the maximum permissible fuses for each SIRIUS control.

If a fuse is used with a higher rated current than specified, semiconductor protection is no longer guaranteed. However, smaller fuses with a lower rated current for the load can be used without problems.
For protective devices with gG operational class and for SITOR 3NE1 all-range fuses, the minimum cross-sections for the conductor to be connected must be taken into account.

| Order No. | All-range fuses |  | Semiconductor fuses/partial-range fuses |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | LV HRC design gR/SITOR <br> 3NE1 | Cylindrical design gR/NEOZED ${ }^{2)}$ <br> SILIZED 5SE1 | LV HRC design aR/SITOR 3NE8 | Cylindrical design aR/SITOR <br> $10 \mathrm{~mm} \times 38 \mathrm{~mm}$ 3NC1 0 | aR/SITOR <br> $14 \mathrm{~mm} \times 51 \mathrm{~mm}$ 3NC1 4 | aR/SITOR <br> $22 \mathrm{~mm} \times 58 \mathrm{~mm}$ 3NC2 2 |
| $\begin{aligned} & \text { 3RF21 20-... } 2 \\ & \text { 3RF21 20-.. } 4 \\ & \text { 3RF21 20-... } 5^{3} \end{aligned}$ | 3NE1 814-0 <br> 3NE1 813-04) <br> 3NE1 813-04) | 5SE1 325 5SE1 320 5SE1 320 | $\begin{aligned} & \text { 3NE8 015-1 } \\ & \text { 3NE8 015-1 } \\ & \text { 3NE8 015-1 } \end{aligned}$ | $\begin{aligned} & \hline \text { 3NC1 020 } \\ & \text { 3NC1 016 } \\ & \text { 3NC1 0164) } \end{aligned}$ | $\begin{aligned} & \text { 3NC1 420 } \\ & \text { 3NC1 } 420 \\ & \text { 3NC1 } 420 \end{aligned}$ | $\begin{aligned} & \hline \text { 3NC2 } 220 \\ & \text { 3NC2 } 220 \\ & \text { 3NC2 } 220 \\ & \hline \end{aligned}$ |
| 3RF21 30-...2 3RF21 30-.. 4 3RF21 30-...5) 3RF21 30-... | $\begin{aligned} & \text { 3NE1 815-0 }{ }^{4)} \\ & \text { 3NE1 } 815-0^{4)} \\ & \text { 3NE1 } 815-0^{4)} \\ & \text { 3NE1 } 815-0^{4)} \end{aligned}$ | $\begin{aligned} & \text { 5SE1 } 335 \\ & \text { 5SE1 } 325^{4)} \\ & \text { 5SE1 } 325^{4)} \end{aligned}$ -- | 3NE8 003-1 <br> 3NE8 003-1 <br> 3NE8 003-1 <br> 3NE8 003-1 | $\begin{aligned} & \text { 3NC1 O32 } \\ & 3 N C 1025^{4)} \\ & 3 N C 10254 \\ & 3 N C 1032 \end{aligned}$ | $\begin{aligned} & \text { 3NC1 } 432 \\ & \text { 3NC1 430 } \\ & \text { 3NC1 } 430 \\ & \text { 3NC1 } 432 \end{aligned}$ | $\begin{aligned} & \text { 3NC2 } 232 \\ & \text { 3NC2 } 232 \\ & \text { 3NC2 } 232 \\ & \text { 3NC2 } 232 \end{aligned}$ |
| 3RF21 50-...2 3RF21 50-..4 3RF21 50-...5 3RF21 50-... | 3NE1 817-0 <br> 3NE1 802-04) <br> 3NE1 802-04) <br> 3NE1 803-04) | $\begin{aligned} & \text { 5SE1 } 350 \\ & \text { 5SE1 } 335^{4)} \\ & \text { 5SE1 } 335^{4)} \\ & -- \\ & \hline \end{aligned}$ | 3NE8 017-1 <br> 3NE8 017-1 <br> 3NE8 017-1 <br> 3NE8 017-1 |  | 3NC1 450 <br> 3NC1 450 <br> 3NC1 450 <br> 3NC1 450 | $\begin{aligned} & \text { 3NC2 } 250 \\ & \text { 3NC2 } 250 \\ & \text { 3NC2 } 250 \\ & \text { 3NC2 } 250 \end{aligned}$ |
| 3RF21 70-...25) 3RF21 70-...4) 3RF21 70-...5)5) 3RF21 70-... ${ }^{5)}$ | 3NE1 820-0 <br> 3NE1 020-2 <br> 3NE1 020-2 <br> 3NE1 020-2 | 5SE1 3634) $5 \text { SE1 } 363^{4)}$ | 3NE8 020-1 <br> 3NE8 020-1 <br> 3NE8 020-1 <br> 3NE8 020-1 | -- |  | $\begin{aligned} & \text { 3NC2 } 280 \\ & \text { 3NC2 } 280 \\ & \text { 3NC2 } 280 \\ & \text { 3NC2 } 280 \end{aligned}$ |
| 3RF21 90-...25) 3RF21 $90-\ldots 4^{5}$ 3RF21 $90-\ldots .5^{3) 5)}$ 3RF21 $90-\ldots 6^{5}$ | 3NE1 021-2 <br> 3NE1 021-2 <br> 3NE1 021-2 <br> 3NE1 817-0 ${ }^{4)}$ | -- | $\begin{aligned} & \text { 3NE8 021-1 } \\ & \text { 3NE8 021-1 } \\ & \text { 3NE8 021-1 } \\ & \text { 3NE8 021-1 } \end{aligned}$ | -- | -- | $\begin{aligned} & \text { 3NC2 200 } \\ & 3 N C 2280^{4)} \\ & 3 N C 2280^{4)} \\ & 3 N C 2280^{4)} \end{aligned}$ |



Suitable fuse holders, fuse bases and controls can be found in
Catalog LV 1, Chapter 19.

1) Type of coordination "2" according to EN 60947-4-1: In the event of a short-circuit, the controls in the load feeder must not endanger persons or the installation. They must be suitable for further operation. For fused configurations, the protective device must be replaced.
2) For use only with operational voltage $U_{e}$ up to 400 V .
3) For use only with operational voltage $U_{e}$ up to 506 V .
4) These fuses have a smaller rated current than the solid-state relays
5) These versions can also be protected against short-circuits with miniature circuit breakers as described in the notes on "SIRIUS Solid-State Contactors $\rightarrow$ Special Version Short-Circuit Resistant".

## Solid-State Switching Devices for Resistive Loads Solid-State Relays

## 3RF21 solid-state relays, single-phase, 22.5 mm

Characteristic curves
Dependence of the device current $I_{\mathrm{e}}$ on the ambient temperature $T_{\mathrm{a}}$ and the heat sink resistance $R_{\text {thha }}$


Type current 20 A (3RF21 20, 3RF20 20) ${ }^{1)}$


Type current 30 A (3RF21 30, 3RF20 30)


Type current 50 A (3RF21 50, 3RF20 50)

1) For arrangement example see next page.

## Solid-State Switching Devices for Resistive Loads

 Solid-State Relays

Type current 70 A (3RF21 70, 3RF20 70)


Type current 90 A (3RF21 90, 3RF20 90)
Arrangement example
Given conditions: $I_{\mathrm{e}}=20 \mathrm{~A}$ and $T_{\mathrm{a}}=40 \mathrm{C}$. The task is to find the thermal resistance $R_{\text {thha }}$ and the heat sink overtemperature $d T_{\text {ha }}$.
From the diagram on the left $\rightarrow P_{\mathrm{M}}=28 \mathrm{~W}$,
from the diagram on the right $\rightarrow R_{\text {thha }}=2.0 \mathrm{~K} / \mathrm{W}$.
This results in:
$d T_{\text {ha }}=R_{\text {thha }} \times \mathrm{PM}=2.0 \mathrm{~K} / \mathrm{W} \times 28 \mathrm{~W}=56 \mathrm{~K}$.
At $d T_{\text {ha }}=56 \mathrm{~K}$ the heat sink must therefore have an
$R_{\text {thha }}=2.0 \mathrm{~K} / \mathrm{W}$.

Solid-State Switching Devices for Resistive Loads Solid-State Relays

## 3RF21 solid-state relays, single-phase, 22.5 mm

## Dimensional drawings

Solid-state relays


Terminal cover
3RF29 00-3PA88


## Schematics

Version
DC control supply voltage


Version
AC control supply voltage


Switching example


## Solid-State Switching Devices for Resistive Loads

Solid-State Relays

## Overview

## 45 mm solid-state relays

The solid-state relays with a width of 45 mm provide for connection of the power supply lead and the load from above. This makes it easy to replace existing solid-state relays in existing arrangements. The connection of the control cable also saves space in much the same way as the 22.5 mm design, as it is simply plugged on.

## Technical specifications

| Type |  | 3RF20 ..-1.... | 3RF20 ..-4.... |
| :---: | :---: | :---: | :---: |
| General data |  |  |  |
| Ambient temperature <br> - During operation, derating from $40^{\circ} \mathrm{C}$ <br> - During storage | $\begin{aligned} & { }^{\circ} \mathrm{C} \\ & { }^{\circ} \mathrm{C} \end{aligned}$ | $\begin{aligned} & -25 \ldots+60 \\ & -55 \ldots+80 \end{aligned}$ |  |
| Installation altitude | m | 0 ... 1000; derating from 1000 |  |
| Shock resistance acc. to IEC 60068-2-27 | $\mathrm{g} / \mathrm{ms}$ | 15/11 |  |
| Vibration resistance acc. to IEC 60068-2-6 | $g$ | 2 |  |
| Degree of protection |  | IP20 |  |
| Electromagnetic compatibility (EMC) <br> - Emitted interference <br> - Conducted interference voltage acc. to IEC 60947-4-3 <br> - Emitted, high-frequency interference voltage acc. to IEC 60947-4-3 |  | Class A for industrial applications <br> Class A for industrial applications |  |
| - Interference immunity <br> - Electrostatic discharge acc. to IEC 61000-4-2 (corresponds to degree of severity 3 ) <br> - Induced RF fields acc. to IEC 61000-4-6 <br> - Burst acc. to IEC 61000-4-4 <br> - Surge acc. to IEC 61000-4-5 | kV <br> MHz <br> kV <br> kV | Contact discharge 4; air discharge 8; <br> 0.15 ... 80; $140 \mathrm{~dB} \mu \mathrm{~V}$; behavior criterio <br> 2/5.0 kHz; behavior criterion 1 <br> Conductor - ground 2; conductor - co | $\text { on } 2$ <br> vior criterion 2 |
| Connection type |  | $\bigoplus$ Screw terminals | OO Spring-type terminals |
| Connection, main contacts <br> - Conductor cross-section <br> - Solid <br> - Finely stranded with end sleeve <br> - Solid or stranded, AWG cables <br> - Terminal screw <br> - Tightening torque | $\begin{aligned} & \mathrm{mm}^{2} \\ & \mathrm{~mm}^{2} \end{aligned}$ <br> Nm lb.in | $\begin{aligned} & \left.\left.2 \times(1.5 \ldots 2.5)^{1}\right), 2 \times(2.5 \ldots 6)^{1}\right) \\ & 2 \times(1 \ldots 2.5)^{1}, 2 \times(2.5 \ldots 6)^{1}, 1 \times 10 \\ & 2 \times(\text { AWG } 14 \ldots 10) \\ & \text { M4 } \\ & 2 \ldots 2.5 \\ & 7 \ldots 10.3 \end{aligned}$ |  |
| Connection, auxiliary/control contacts <br> - Conductor cross-section | $\mathrm{mm}^{2}$ | $1 \times(0.5 \ldots 2.5), 2 \times(0.5 \ldots 1.0)$ $\text { AWG } 20 \text {... } 12$ | 0.5 ... 2.5, AWG 20 ... 12 |
| - Stripped length <br> - Terminal screw <br> - Tightening torque | mm <br> Nm <br> lb.in | $\begin{array}{ll} 7 & \\ \text { M3 } & \\ 0.5 \ldots & 0.6 \\ 4.5 \ldots . & 5.3 \end{array}$ | $10$ |

1) If two different conductor cross-sections are connected to one clamping point, both cross-sections must lie in the range specified. If identical cross-sections are used, this restriction does not apply.

## Solid-State Switching Devices for Resistive Loads

Solid-State Relays

## 3RF20 solid-state relays, single-phase, 45 mm

| Order No. | $\begin{aligned} & \boldsymbol{I}_{\text {max }} \mathbf{1} \\ & \text { at } R_{\text {thha }} / T_{u}=40^{\circ} \mathrm{C} \end{aligned}$ |  | $I_{\text {e }}$ acc. to IEC 60947-4-3 at $R_{\text {thha }} / T_{u}=40^{\circ} \mathrm{C}$ |  | $I_{\mathrm{e}}$ acc. to UL/CSA at $\mathrm{R}_{\text {thha }} / \mathrm{T}_{\mathrm{u}}=50^{\circ} \mathrm{C}$ |  | Power loss at $I_{\text {max }}$ | Minimum load current | Leakage current |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | A | K/W | A | K/W | A | K/W | W | A | mA |
| Main circuit |  |  |  |  |  |  |  |  |  |
| 3RF20 20-1.A.. | 20 | 2.0 | 20 | 1.7 | 20 | 1.3 | 28.6 | 0.1 | 10 |
| 3RF20 30-1.A.. | 30 | 1.1 | 30 | 0.79 | 30 | 0.56 | 44.2 | 0.5 | 10 |
| 3RF20 50-1.A.. | 50 | 0.68 | 50 | 0.48 | 50 | 0.33 | 66 | 0.5 | 10 |
| 3RF20 70-1.A.. | 70 | 0.40 | 50 | 0.77 | 50 | 0.6 | 94 | 0.5 | 10 |
| 3RF20 90-1.A.. | 88 | 0.33 | 50 | 0.94 | 50 | 0.85 | 118 | 0.5 | 10 |
| 1) $I_{\max }$ provides information about the performance of the solid-state relay. The actual permitted rated operational current $I_{\mathrm{e}}$ can be smaller depending on the connection method and cooling conditions. |  |  |  |  |  | Note: The required heat sinks for the corresponding load currents can be determined from the characteristic curves, page 12. The minimum thickness values for the mounting surface must be observed. |  |  |  |


| Order No. | Rated impulse withstand capacity $\boldsymbol{I}_{\text {tsm }}$ | $\boldsymbol{I}^{\mathbf{2} \mathbf{t} \text { value }}$ |
| :--- | :--- | :--- |
|  | A | $\mathrm{A}^{2} \mathrm{~s}$ |
| Main circuit |  |  |
| 3RF20 20-1.A.. | 200 | 200 |
| 3RF20 30-1.A.2 | 300 | 450 |
| 3RF20 30-1.A.4 | 300 | 450 |
| 3RF20 30-1.A.6 | 400 | 800 |
| 3RF20 50-1.A.. | 600 | 1800 |
| 3RF20 70-1.A.2 | 1200 | 7200 |
| 3RF20 70-1.A.4 | 1200 | 7200 |
| 3RF20 70-1.A.5 | 1200 | 7200 |
| 3RF20 70-1.A.6 | 1150 | 6600 |
| 3RF20 90-1.A.. | 1150 | 6600 |


| Type |  | 3RF20 .0-1.A. 2 | 3RF20 .0-1.A. 4 | 3RF20 .0-1.A. 5 | 3RF20 .0-1.A. 6 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Main circuit |  |  |  |  |  |
| Rated operational voltage $\boldsymbol{U}_{\mathbf{e}}$ | V | $24 . .230$ | 48 ... 460 | 48 ... 600 | $48 . . .600$ |
| - Operating range | V | $20 . . .253$ | 40 ... 506 | 40 ... 660 | 40 ... 660 |
| - Rated frequency | Hz | 50/60 $\pm 10$ \% |  |  |  |
| Rated insulation voltage $\boldsymbol{U}_{\mathbf{i}}$ | V | 600 |  |  |  |
| Blocking voltage | V | 800 | 1200 |  | 1600 |
| Rage of voltage rise | V/ $/$ s | 1000 |  |  |  |


| Type |  | 3RF20 .0-1.A0. | 3RF20 .0-1.A2. | 3RF20 .0-1.A4. |
| :---: | :---: | :---: | :---: | :---: |
| Control circuit |  |  |  |  |
| Method of operation |  | DC operation | AC operation | DC operation |
| Rated control supply voltage $\boldsymbol{U}_{\mathbf{S}}$ | V | 24 acc. to EN 61131-2 | 110... 230 | $4 \ldots 30$ |
| Rated frequency of the control supply voltage | Hz | -- | 50/60 $\pm 10$ \% | -- |
| Control supply voltage, max. | V | 30 | 253 | 30 |
| Typical actuating current | mA | 20 | 15 | 20 |
| Response voltage | V | 15 | 90 | 4 |
| Drop-out voltage | V | 5 | 40 | 1 |
| Operating times |  |  |  |  |
| - ON-delay | ms | $1+$ max. one half-wave ${ }^{1)}$ | 40 + max. one half-wave ${ }^{1)}$ | $1+$ max. one half-wave ${ }^{1)}$ |
| - OFF-delay | ms | 1 + max. one half-wave | 40 + max. one half-wave | 1 + max. one half-wave |

1) Only for zero-point-switching devices.

## Fused version with semiconductor protection (similar to type of coordination "2")1)

The semiconductor protection for the SIRIUS controls can be used with different protective devices. This allows protection by means of LV HRC fuses of gG operational class or miniature circuit breakers. Siemens recommends the use of special SITOR semiconductor fuses. The table below lists the maximum permissible fuses for each SIRIUS control.

If a fuse is used with a higher rated current than specified, semiconductor protection is no longer guaranteed. However, smaller fuses with a lower rated current for the load can be used without problems.
For protective devices with gG operational class and for SITOR 3NE1 all-range fuses, the minimum cross-sections for the conductor to be connected must be taken into account.

| Order No. | All-range fuses |  | Semiconductor fuses/partial-range fuses |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | LV HRC design gR/SITOR <br> 3NE1 | Cylindrical design gR/NEOZED ${ }^{2)}$ <br> SILIZED 5SE1 | LV HRC design aR/SITOR 3NE8 | Cylindrical design aR/SITOR <br> $10 \mathrm{~mm} \times 38 \mathrm{~mm}$ 3NC1 0 | aR/SITOR <br> $14 \mathrm{~mm} \times 51 \mathrm{~mm}$ 3NC1 4 | aR/SITOR <br> $22 \mathrm{~mm} \times 58 \mathrm{~mm}$ 3NC2 2 |
| $\begin{aligned} & \hline \text { 3RF20 20-1.A. } 2 \\ & \text { 3RF20 20-1.A. } \\ & \text { 3RF20 20-1.A. }{ }^{3} \end{aligned}$ | $\begin{aligned} & \hline 3 \text { NE1 814-0 } \\ & 3 \text { NE1 813-0 } \\ & 3 \text { NE1 813-0 } \\ & \hline \end{aligned}$ | 5SE1 325 <br> 5SE1 320 <br> 5SE1 320 | $\begin{array}{ll} \hline 3 \text { NE8 015-1 } \\ 3 \text { NE8 } & 015-1 \\ 3 \text { NE8 015-1 } \end{array}$ | $\begin{aligned} & \hline \text { 3NC1 020 } \\ & \text { 3NC1 016 } \\ & \text { 3NC1 0164) } \end{aligned}$ | 3NC1 420 <br> 3NC1 420 <br> 3NC1 420 | $\begin{aligned} & \text { 3NC2 } 220 \\ & \text { 3NC2 } 220 \\ & \text { 3NC2 } 220 \end{aligned}$ |
| $\begin{aligned} & \text { 3RF20 30-1.A. } 2 \\ & \text { 3RF20 30-1.A. } 4 \\ & \text { 3RF20 30-1.A. } 6 \end{aligned}$ | $\begin{aligned} & 3 \text { NE1 815-04) } \\ & \text { 3 NE1 815-0 } \\ & \text { 3 NE1 815-04) } \end{aligned}$ | $\begin{aligned} & \text { 5SE1 335 } \\ & \text { 5SE1 3254) } \end{aligned}$ | $\begin{aligned} & 3 \text { NE8 003-1 } \\ & 3 \text { NE8 003-1 } \\ & 3 \text { NE8 003-1 } \end{aligned}$ | $\begin{aligned} & \text { 3NC1 } 032 \\ & \text { 3NC1 } 025^{4)} \\ & \text { 3NC1 } 032 \end{aligned}$ | $\begin{aligned} & \text { 3NC1 } 432 \\ & \text { 3NC1 } 430 \\ & \text { 3NC1 } 432 \end{aligned}$ | 3NC2 232 <br> 3NC2 232 <br> 3NC2 232 |
| $\begin{aligned} & \text { 3RF20 50-1.A. } 2 \\ & \text { 3RF20 50-1.A. } 4 \\ & \text { 3RF20 50-1.A. }{ }^{3} \\ & \text { 3RF20 50-1.A. } 6 \end{aligned}$ | 3 NE1 817-0 <br> 3 NE1 802-04) <br> 3 NE1 802-04) <br> 3 NE1 803-04) | 5SE1 350 <br> 5SE1 3354) <br> 5SE1 3354) <br> -- | 3 NE8 017-1 <br> 3 NE8 017-1 <br> 3 NE8 017-1 <br> 3 NE8 017-1 |  | 3NC1 450 <br> 3NC1 450 <br> 3NC1 450 <br> 3NC1 450 | $\begin{aligned} & \hline \text { 3NC2 } 250 \\ & \text { 3NC2 } 250 \\ & \text { 3NC2 } 250 \\ & \text { 3NC2 } 250 \end{aligned}$ |
| $\begin{aligned} & \text { 3RF20 70-1.A.2 }{ }^{5)} \\ & \text { 3RF20 70-1.A.4 } 4^{5)} \\ & \text { 3RF20 70-1.A.5 } \mathbf{5}^{35)} \\ & \text { 3RF20 70-1.A. } \mathbf{6}^{5)} \end{aligned}$ | $\begin{aligned} & 3 \text { NE1 820-0 } \\ & 3 \text { NE1 O20-2 } \\ & 3 \text { NE1 020-2 } \\ & 3 \text { NE1 O20-2 } \end{aligned}$ | $\begin{aligned} & \text { 5SE1 } 363^{4)} \\ & \text { 5SE1 } 363^{4)} \end{aligned}$ | 3 NE8 020-1 3 NE8 020-1 3 NE8 020-1 3 NE8 020-1 |  | -- | $\begin{aligned} & \text { 3NC2 } 280 \\ & \text { 3NC2 } 280 \\ & \text { 3NC2 } 280 \\ & \text { 3NC2 } 280 \end{aligned}$ |
| $\begin{aligned} & \text { 3RF20 90-1.A.2 }{ }^{5)} \\ & \text { 3RF20 90-1.A.4 } 4^{5)} \\ & \text { 3RF20 90-1.A.5 } \mathbf{5}^{35)} \\ & \text { 3RF20 90-1.A. } \mathbf{6}^{5)} \end{aligned}$ | 3 NE1 021-2 <br> 3 NE1 021-2 <br> 3 NE1 021-2 <br> 3 NE1 817-0 ${ }^{4}$ | -- -- -- | $\begin{aligned} & 3 \text { NE8 021-1 } \\ & 3 \text { NE8 021-1 } \\ & 3 \text { NE8 021-1 } \\ & 3 \text { NE8 021-1 } \end{aligned}$ | -- | -- -- -- -- | $\begin{aligned} & \text { 3NC2 } 200 \\ & \text { 3NC2 } 280^{4)} \\ & \text { 3NC2 } 280^{4} \\ & \text { 3NC2 2804) } \end{aligned}$ |


| Order No. | Cable and line protection fuses |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | LV HRC design ${ }^{4}$ | Cylindrical design ${ }^{4}$ |  |  | DIAZED ${ }^{4)}$ |
|  | gG | gG | gG | gG | quick |
|  | 3NA2 | $10 \mathrm{~mm} \times 38 \mathrm{~mm}$ 3NW6 0 | $14 \mathrm{~mm} \times 51 \mathrm{~mm}$ 3NW6 1 | $22 \mathrm{~mm} \times 58 \mathrm{~mm}$ 3NW6 2 | 5SB |
| 3RF20 20-1.A. 2 | 3NA2 803 | 3NW6 001-1 | 3NW6 101-1 | -- | 5SB1 41 |
| 3RF20 20-1.A. 4 | 3NA2 801 | -- | 3NW6 101-1 | -- | 5SB1 41 |
| 3RF20 20-1.A.5 ${ }^{3}$ | 3NA2 801 | -- | 3NW6 101-1 | -- | 5SB141 |
| 3RF20 30-1.A. 2 | 3NA2 803 | -- | 3NW6 103-1 | -- | 5SB1 71 |
| 3RF20 30-1.A. 4 | 3NA2 803 | -- | 3NW6 101-1 | -- | 5SB1 71 |
| 3RF20 30-1.A. 6 | 3NA2 803-6 | -- | -- | -- | -- |
| 3RF20 50-1.A. 2 | 3NA2 810 | -- | 3NW6 107-1 | 3NW6 207-1 | 5SB3 11 |
| 3RF20 50-1.A. 4 | 3NA2 807 | -- | -- | 3NW6 205-1 | 5SB3 11 |
| 3RF20 50-1.A.5 ${ }^{3}$ | 3NA2 807 | -- | -- | 3NW6 205-1 | 5SB3 11 |
| 3RF20 50-1.A. 6 | 3NA2 807-6 | -- | -- | -- | -- |
| 3RF20 70-1.A.2 ${ }^{5}$ | 3NA2 817 | -- | -- | 3NW6 217-1 | 5SB3 31 |
| 3RF20 70-1.A.4 ${ }^{5}$ | 3NA2 812 | -- | -- | 3NW6 212-1 | 5SB3 31 |
| 3RF20 70-1.A.5 ${ }^{3) 5}$ | 3NA2 812 | -- | -- | 3NW6 212-1 | -- |
| 3RF20 70-1.A.6 ${ }^{5}$ | 3NA2 812-6 | -- | -- |  | -- |
| 3RF20 90-1.A. ${ }^{5)}$ | 3NA2 817 | -- | -- | 3NW6 217-1 | -- |
| 3RF20 90-1.A.4 ${ }^{5}$ | 3NA2 812 | -- | -- | 3NW6 212-1 | -- |
| 3RF20 90-1.A.5 ${ }^{3) 5}$ | 3NA2 812 | -- | -- | 3NW6 212-1 | -- |
| 3RF20 90-1.A.6 ${ }^{5}$ | 3NA2 812-6 | -- | -- | -- | -- |

Suitable fuse holders, fuse bases and controls can be found in Catalog LV 1, Chapter 19.

1) Type of coordination "2" according to EN 60947-4-1: In the event of a short-circuit, the controls in the load feeder must not endanger persons or the installation. They must be suitable for further operation. For fused configurations, the protective device must be replaced.
2) For use only with operational voltage $U_{e}$ up to 400 V
3) For use only with operational voltage $U_{e}$ up to 506 V .
4) These fuses have a smaller rated current than the solid-state relays.
5) These versions can also be protected against short-circuits with miniature circuit breakers as described in the notes on "SIRIUS Solid-State Contactors $\rightarrow$ Special Version Short-Circuit Resistant".

## 3RF20 solid-state relays, single-phase, 45 mm

## Dimensional drawings



## Schematics

Version
DC control supply voltage


Version
AC control supply voltage


Switching example


## Overview

## 45 mm solid-state relays

The 3RF22 solid-state relays with a width of 45 mm provide space advantages over solutions with single-phase versions. The logical connection method, with the power infeed from above and load connection from below, ensures tidy installation in the control cabinet.

Important features:

- LED display
- Variety of connection methods
- Plug-in control connection
- Degree of protection IP20
- Zero-point switching
- Two- or three-phase controlled

Technical specifications

| Type |  | 3RF22 ..-1.... | 3RF22 ..-2.... | 3RF22 ..-3.... |
| :---: | :---: | :---: | :---: | :---: |
| General data |  |  |  |  |
| Ambient temperature |  |  |  |  |
| - During operation, derating from $40^{\circ} \mathrm{C}$ | ${ }^{\circ} \mathrm{C}$ | $-25 \ldots+60$ |  |  |
| - During storage | ${ }^{\circ} \mathrm{C}$ | $-55 \ldots+80$ |  |  |
| Installation altitude | m | 0 ... 1000; > 1000 ask Technical | ssistance |  |
| Shock resistance acc. to IEC 60068-2-27 | $\mathrm{g} / \mathrm{ms}$ | 15/11 |  |  |
| Vibration resistance acc. to IEC 60068-2-6 | $g$ | 2 |  |  |
| Degree of protection |  | IP20 |  |  |
| Insulation strength at $50 / 60 \mathrm{~Hz}$ (main/control circuit to floor) | V rms | 4000 |  |  |
| Electromagnetic compatibility (EMC) |  |  |  |  |
| - Emitted interference <br> - Conducted interference voltage acc. to IEC 60947-4-3 <br> - Emitted, high-frequency interference voltage acc. to IEC 60947-4-3 |  | Class A for industrial application Class A for industrial application | 1) |  |
| - Interference immunity <br> - Electrostatic discharge acc. to IEC 61000-4-2 (corresponds to degree of severity 3 ) <br> - Induced RF fields acc. to IEC 61000-4-6 <br> - Burst acc. to IEC 61000-4-4 <br> - Surge acc. to IEC 61000-4-5 | kV <br> MHz <br> kV <br> kV | Contact discharge 4; air dischar <br> 0.15 ... 80; $140 \mathrm{~dB} \mu \mathrm{~V}$; behavior <br> 2/5.0 kHz; behavior criterion 1 Conductor - ground 2; conducto | 8; behavior criterion 2 <br> terion 1 <br> - conductor 1; behavior criterio |  |
| Connection type |  | (i) Screw terminals | Spring-type terminals | Ring terminal lug connection |
| Connection, main contacts |  |  |  |  |
| - Conductor cross-section <br> - Solid <br> - Finely stranded with end sleeve <br> - Finely stranded without end sleeve <br> - Solid or stranded, AWG cables | $\begin{aligned} & \mathrm{mm}^{2} \\ & \mathrm{~mm}^{2} \\ & \mathrm{~mm}^{2} \end{aligned}$ | $\begin{aligned} & \left.2 \times(1.5 \ldots 2.5)^{2)}, 2 \times(2.5 \ldots 6)^{2}\right) \\ & 2 \times(1 \ldots 2.5)^{2)}, 2 \times(2.5 \ldots 6)^{2}, \\ & 1 \times 10 \\ & -- \\ & 2 \times(\text { AWG } 14 \ldots 10) \end{aligned}$ | $\begin{aligned} & 2 \times\left(\begin{array}{lll} 0.5 & \ldots & 2.5) \\ 2 \times(0.5 \ldots & 1.5 \end{array}\right) \\ & 2 \times(0.5 \ldots 2.5) \\ & 2 \times(\text { AWG } 18 \ldots 14) \end{aligned}$ |  |
| - Stripped length | mm |  |  |  |
| - Terminal screw - Tightening torque, $\varnothing 5 \ldots 6 \mathrm{~mm}, \mathrm{PZ} 2$ | Nm lb.in | M4 <br> 2 ... 2.5 <br> 18 ... 22 | -- | $\begin{aligned} & \text { M5 } \\ & 2.5 \ldots 2 \\ & 18 \ldots 22 \end{aligned}$ |
| - Cable lug <br> - Acc. to DIN 46234 <br> - Acc. to JIS C 2805 |  | -- | -- | $\begin{aligned} & 5-2.5 \ldots 5 \\ & \text { R } 2-5 \ldots \\ & \hline \end{aligned}$ |
| Connection, auxiliary/control contacts |  |  |  |  |
| - Conductor cross-section, with or without end sleeve | mm <br> AWG | $\begin{aligned} & 1 \times(0.5 \ldots 2.5), 2 \times(0.5 \ldots 1.0) \\ & 20 \ldots 12 \end{aligned}$ | $\begin{aligned} & 0.5 \ldots 2.5 \\ & 20 \ldots 12 \end{aligned}$ | $\begin{aligned} & 1 \times(0.5 \ldots 2.5), 2 \times(0.5 \ldots 1.0) \\ & 20 \ldots 12 \end{aligned}$ |
| - Stripped length | mm | 7 | 10 | 7 |
| - Terminal screw <br> - Tightening torque, $\varnothing 3.5$, PZ 1 | Nm lb.in | $\begin{aligned} & \text { M3 } \\ & 0.5 \ldots 0.6 \\ & 4.5 \ldots 5.3 \end{aligned}$ | -- | $\begin{aligned} & \text { M3 } \\ & 0.5 \ldots 0.6 \\ & 4.5 \ldots 5.3 \end{aligned}$ |

1) These products were built as Class $A$ devices. The use of these devices in residential areas could result in lead in radio interference. In this case these may be required to introduce additional interference suppression measures.
2) If two different conductor cross-sections are connected to one clamping point, both cross-sections must lie in the range specified. If identical cross-sections are used, this restriction does not apply.

## Solid-State Switching Devices for Resistive Loads

Solid-State Relays

## 3RF22 solid-state relays, three-phase, 45 mm

| Order No. | $\begin{aligned} & \boldsymbol{I}_{\text {max }}^{\mathbf{1}} \\ & \text { at } R_{\text {thha }} / T_{\mathrm{u}}=40^{\circ} \mathrm{C} \end{aligned}$ |  | $I_{\mathrm{e}}$ acc. to IEC 60947-4-3 at $R_{\text {thna }} / T_{\mathrm{u}}=40^{\circ} \mathrm{C}$ |  | $I_{\mathrm{e}}$ acc. to UL/CSA at $R_{\text {thha }} / T_{\mathrm{u}}=50^{\circ} \mathrm{C}$ |  | Power loss at $I_{\text {max }}$ | Minimum load current | Max. leakage current |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | A | K/W | A | K/W | A | K/W | W | A | mA |
| Main circuit |  |  |  |  |  |  |  |  |  |
| 3RF22 30-. AB.. | 30 | 0.57 | 30 | 0.57 | 30 | 0.44 | 81 | 0.5 | 10 |
| $\begin{aligned} & \text { 3RF22 55-1AB.. } \\ & \text { 3RF22 55-2AB.. } \\ & \text { 3RF22 55-3AB.. } \end{aligned}$ | 55 | 0.18 | $\begin{aligned} & 50 \\ & 20 \\ & 50 \end{aligned}$ | $\begin{aligned} & 0.27 \\ & 1.83 \\ & 0.27 \end{aligned}$ | $\begin{aligned} & 50 \\ & 20 \\ & 50 \end{aligned}$ | $\begin{aligned} & 0.19 \\ & 1.58 \\ & 0.19 \end{aligned}$ | 151 | 0.5 | 10 |
| 3RF22 30-. AC.. | 30 | 0.33 | 30 | 0.33 | 30 | 0.25 | 122 | 0.5 | 10 |
| 3RF22 55-1AC. 3RF22 55-2AC. 3RF22 55-3AC. | 55 | 0.09 | $\begin{aligned} & 50 \\ & 20 \\ & 50 \end{aligned}$ | $\begin{aligned} & 0.15 \\ & 1.19 \\ & 0.15 \end{aligned}$ | $\begin{aligned} & 50 \\ & 20 \\ & 50 \end{aligned}$ | $\begin{aligned} & 0.1 \\ & 1.02 \\ & 0.1 \end{aligned}$ | 226 | 0.5 | 10 |

1) Imax provides information about the performance of the solid-state relay. The actual permitted rated operational current $I_{\mathrm{e}}$ can be smaller depending on the connection method and cooling conditions.

Note: The required heat sinks for the corresponding load currents can be determined from the characteristic curves, page 22. The minimum thickness values for the mounting surface must be observed.

| Order No. | Rated impulse withstand capacity $\boldsymbol{I}$ tsm | $\boldsymbol{I}^{\mathbf{2} \mathbf{t} \text { value }}$ |
| :--- | :--- | :--- |
|  | A | $\mathrm{A}^{2} \mathrm{~S}$ |
| Main circuit |  |  |
| 3RF22 $\mathbf{3 0}-\ldots .5$ | 300 | 450 |
| 3RF22 55-...5 | 600 | 1800 |


| Type |  | 3RF22 ..-.AB.5 | 3RF22 ..-.AC. 5 |
| :--- | :--- | :--- | :--- |
| Main circuit |  |  | Two-phase |
| Controlled phases | V | $48 \ldots 600$ | Three-phase |
| Rated operational voltage $\boldsymbol{U}_{\mathrm{e}}$ | V | $40 \ldots 660$ | $48 \ldots 600$ |
| $\bullet$ Operating range | Hz | $50 / 60 \pm 10 \%$ | $40 \ldots 660$ |
| - Rated frequency | V | 600 | $50 / 60 \pm 10 \%$ |
| Rated insulation voltage $\boldsymbol{U}_{\mathrm{i}}$ | kV | 6 | 600 |
| Rated impulse withstand voltage $\boldsymbol{U}_{\mathrm{imp}}$ | V | 1200 | 6 |
| Blocking voltage | $\mathrm{V} / \mathrm{\mu s}$ | 1000 | 1200 |
| Rage of voltage rise |  |  | 1000 |


| Type |  | 3RF22 ..-.A.3. | 3RF22 ..-.A.4. |
| :--- | :--- | :--- | :--- |
| Control circuit | V | 110 | DC operation |
| Method of operation |  | $50 / 60 \pm 10 \%$ | $4 \ldots 30$ |
| Rated control supply voltage $\boldsymbol{U}_{\mathbf{s}}$ | V | 121 | -- |
| Rated frequency <br> of the control supply voltage | mA | 15 | 30 |
| Control supply voltage, max. | V | 90 | 30 |
| Typical actuating current | V | $<40$ | 4 |
| Response voltage |  |  | 1 |
| Drop-out voltage | ms | $40+$ max. one half-wave |  |
| Operating times <br> - ON-delay | ms | $40+$ max. one half-wave | $1+$ max. one half-wave |
| - OFF-delay |  |  | $1+$ max. one half-wave |

## Solid-State Switching Devices for Resistive Loads

Solid-State Relays
3RF22 solid-state relays, three-phase, 45 mm
Fused version with semiconductor protection (similar to type of coordination "2")1)

The semiconductor protection for the 3RF22 controls can be used with different protective devices. Siemens recommends the use of special SITOR semiconductor fuses. The table below lists the maximum permissible fuses for each 3RF22 control.

If a fuse is used with a higher rated current than specified, semiconductor protection is no longer guaranteed. However, smaller fuses with a lower rated current for the load can be used without problems.

| Order No. | All-range fuses LV HRC design gR/SITOR 3NE1 |  | Semiconductor fuses/partial-range fuses |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Cylindrical design gR/NEOZED2) <br> SILIZED 5SE1 | LV HRC design aR/SITOR <br> 3NE8 | Cylindrical design aR/SITOR <br> $10 \mathrm{~mm} \times 38 \mathrm{~mm}$ 3NC1 0 | aR/SITOR <br> $14 \mathrm{~mm} \times 51 \mathrm{~mm}$ 3NC1 4 | aR/SITOR <br> $22 \mathrm{~mm} \times 58 \mathrm{~mm}$ 3NC2 2 |
| Operational voltage $\boldsymbol{U}_{\text {e }}$ up to 460 V (+10\%) |  |  |  |  |  |  |
| $\begin{aligned} & \text { 3RF22 30-..... } \\ & \text { 3RF22 55-.... } \end{aligned}$ | $\begin{aligned} & \text { 3NE1 814-03) } \\ & \text { 3NE1 802-03) } \end{aligned}$ | $\begin{aligned} & \text { 5SE1 } 325^{3)} \\ & \text { 5SE1 } 350^{3)} \end{aligned}$ | 3NE8 003-1 <br> 3NE8 018-1 | $\text { 3NC1 } 032$ | $\begin{aligned} & 3 N C 1430 \\ & 3 N C 1450 \end{aligned}$ | 3NC2 232 <br> 3NC2 263 |
| Operational voltage $U_{\text {e }}$ up to $600 \mathrm{~V}(+10 \%)$ |  |  |  |  |  |  |
| $\begin{aligned} & \text { 3RF22 30-..... } \\ & \text { 3RF22 55-.... } \end{aligned}$ | $\begin{aligned} & \text { 3NE1 814-03) } \\ & \text { 3NE1 803-03) } \end{aligned}$ | -- | 3NE8 003-1 <br> 3NE8 018-1 | 3NC1 0253) | $\begin{aligned} & \text { 3NC1 } 430 \\ & \text { 3NC1 } 450^{3)} \end{aligned}$ | $\begin{aligned} & \text { 3NC2 } 232 \\ & \text { 3NC2 2503) } \end{aligned}$ |
| Order No. | Cable and line protection fuses |  |  |  |  |  |
|  | LV HRC design ${ }^{3)}$ gG 3NA3 | Cylindrical design gG $10 \mathrm{~mm} \times 38 \mathrm{~mm}$ 3NW6 0 | $\begin{aligned} & \mathrm{gG} \\ & 14 \mathrm{~mm} \times 51 \mathrm{~mm} \\ & \text { 3NW6 } 1 \end{aligned}$ | $\begin{aligned} & \text { gG } \\ & 22 \mathrm{~mm} \times 58 \mathrm{~mm} \\ & \text { 3NW6 } 2 \end{aligned}$ | DIAZED ${ }^{3)}$ <br> quick $5 \mathrm{SB}$ |  |
| Operational voltage $U_{\text {e }}$ up to 460 V (+10\%) |  |  |  |  |  |  |
| $\begin{aligned} & \text { 3RF22 30-..... } \\ & \text { 3RF22 55-.... } \end{aligned}$ | 3NA3 803-6 3NA3 807-6 | -- | 3NW6 101-1 | 3NW6 205-1 | $\begin{aligned} & \text { 5SB1 } 71 \\ & \text { 5SB3 } 11 \end{aligned}$ |  |
| Operational voltage $U_{\text {e }}$ up to 600 V (+10\%) |  |  |  |  |  |  |
| 3RF22 30-..... <br> 3RF22 55-..... | 3NA3 803-6 <br> 3NA3 805-6 | -- | -- |  | -- |  |

Suitable fuse holders, fuse bases and controls can be found in
Catalog LV 1, Chapter 19.

1) Type of coordination "2" according to EN 60947-4-1: In the event of a short-circuit, the controls in the load feeder must not endanger persons or the installation. They must be suitable for further operation. For fused configurations, the protective device must be replaced.
2) For use only with operational voltage $U_{e}$ up to 400 V .
3) These fuses have a smaller rated current than the solid-state relays.

## Solid-State Switching Devices for Resistive Loads Solid-State Relays

## 3RF22 solid-state relays, three-phase, 45 mm

Characteristic curves
Dependence of the device current $I_{\mathrm{e}}$ on the ambient temperature $T_{\mathrm{a}}$ and the heat sink resistance $R_{\text {thha }}$ (two-phase controlled)


Type current 30 A (3RF22 30-.AB..)


Type current 55 A (3RF22 55-. AB..)

Dependence of the device current $I_{\mathrm{e}}$ on the ambient temperature $T_{\mathrm{a}}$ and the heat sink resistance $R_{\text {thha }}$ (three-phase controlled)


Type current 30 A (3RF22 30-.AC..)


Type current 55 A (3RF22 55-.AC..)
Arrangement example

Given conditions: $I_{\mathrm{e}}=55 \mathrm{~A}$ and $T_{\mathrm{a}}=40 \mathrm{C}$. The task is to find the thermal resistance $R_{\text {thha }}$ and the heat sink overtemperature $d T_{\text {ha }}$.
From the diagram on the left $\rightarrow P_{M}=227 \mathrm{~W}$,
from the diagram on the right $\rightarrow R_{\text {thha }}=0.09 \mathrm{~K} / \mathrm{W}$.

This results in:
$d T_{\text {ha }}=R_{\text {thha }} \times \mathrm{PM}=0.09 \mathrm{~K} / \mathrm{W} \times 227 \mathrm{~W}=20.4 \mathrm{~K}$.
At $d T_{\text {ha }}=20.4 \mathrm{~K}$ the heat sink must therefore have an $R_{\text {thha }}=0.09 \mathrm{~K} / \mathrm{W}$.

## Solid-State Switching Devices for Resistive Loads

 Solid-State Relays
## 3RF22 solid-state relays, three-phase, 45 mm

## Dimensional drawings

Solid-state relays


Screw terminal
3RF22 ..-1....


Spring-type terminal 3RF22 ..-2...


Ring terminal lug connection 3RF22 ..-3....


## Schematics

Two-phase controlled,
DC control supply voltage


Three-phase controlled,
DC control supply voltage


# Solid-State Switching Devices for Resistive Loads <br> Solid-State Contactors 

## Overview

The complete units consist of a solid-state relay plus optimized heat sink, and are therefore ready to use. They offer defined rated currents to make selection as easy as possible. Depending on the version, current strengths of up to 88 A are achieved. Like all of our solid-state switching devices, one of their particular advantages is their compact and space-saving design.
With their insulated mounting foot they can easily be snapped onto a standard mounting rail, or they can be mounted on support plates with fixing screws. This insulation enables them to be used in circuits with protective extra-low voltage (PELV) or safety extra-low voltage (SELV) in building management. For other applications, such as for extended personal safety, the heat sink can be grounded through a screw terminal.
The solid-state contactors are available in 2 different versions:

- 3RF23 single-phase solid-state contactors,
- 3RF24 three-phase solid-state contactors


## Version for resistive loads, "zero-point switching"

This standard version is often used for switching space heaters on and off

## Version for inductive loads, "instantaneous switching"

In this version the solid-state contactor is specifically matched to inductive loads. Whether it is a matter of frequent actuation of the valves in a filling plant or starting and stopping small operating mechanisms in packet distribution systems, operation is carried out safely and noiselessly.

## Special "Low noise" version

Thanks to a special control circuit, this zero-point-switching special version can be used in public networks up to 16 A without any additional measures such as interference suppressor filters. As a result it conforms to limit value curve class B according to EN 60947-4-3 in terms of emitted interference.

## Special "Short-circuit resistant" version

Skillful matching of the zero-point switching power semiconductor with the performance of the solid-state contactor means that "short-circuit strength" can be achieved with a standard miniature circuit breaker. In combination with a B-type MCB or a conventional line protection fuse, the result is a short-circuit resistant feeder.
In order to achieve problem-free short-circuit protection by means of miniature circuit breakers, however, certain boundary conditions must be observed. As the magnitude and duration of the short-circuit current are determined not only by the short-circuit breaking response of the miniature circuit breaker but also the properties of the wiring system, such as the internal resistance of the input to the network and damping by controls and cables, particular attention must also be paid to these parameters. The necessary cable lengths are therefore shown for the main factor, the line resistance, in the table below.

The following miniature circuit breakers with a type B tripping characteristic and 10 kA or 6 kA breaking capacity protect the 3RF23..-.DA.. solid-state contactors in the event of short-circuits on the load and the specified conductor cross-sections and lengths:

| Rated current of the miniature circuit breaker | Example of type ${ }^{1)}$ | Max. conductor cross-section | Minimum cable length from contactor to load |
| :---: | :---: | :---: | :---: |
| 6 A | $\begin{aligned} & \text { 5SY4 106-6, } \\ & \text { 5SX2 106-6 } \end{aligned}$ | $1 \mathrm{~mm}^{2}$ | 5 m |
| 10 A | 5SY4 110-6, <br> 5SX2 110-6 | $1.5 \mathrm{~mm}^{2}$ | 8 m |
| 16 A | $\begin{aligned} & \text { 5SY4 116-6, } \\ & \text { 5SX2 116-6 } \end{aligned}$ | $1.5 \mathrm{~mm}^{2}$ | 12 m |
| 16 A | 5SY4 116-6, 5SX2 116-6 | 2.5 mm ${ }^{2}$ | 20 m |
| 20 A | $\begin{aligned} & \text { 5SY4 120-6, } \\ & \text { 5SX2 120-6 } \end{aligned}$ | 2.5 mm ${ }^{2}$ | 20 m |
| 25 A | $\begin{aligned} & \text { 5SY4 125-6, } \\ & \text { 5SX2 125-6 } \end{aligned}$ | 2.5 mm ${ }^{2}$ | 26 m |

1) The miniature circuit breakers can be used up to a maximum rated voltage of 480 V !


The setup and installation above can also be used for the solidstate relays with a $I^{2} t$ value of at least $6600 A^{2} s$.

## More information

## Selecting solid-state contactors

The solid-state contactors are selected on the basis of details of the network, the load and the ambient conditions. As the solidstate contactors are already equipped with an optimally matched heat sink, the selection process is considerably simpler than that for solid-state relays.

The following procedure is recommended:

- Determine the rated current of the load and the mains voltage
- Select a solid-state contactor with the same or higher rated current than the load
- Check the correct contactor size with the aid of the rated current diagram, taking account of the installation conditions

Solid-State Switching Devices for Resistive Loads Solid-State Contactors

## 3RF23 solid-state contactors, single-phase

## Technical specifications

| Order No. |  | 3RF23 ..-.A... | 3RF23 ..-.B... | 3RF23 ..-.C... | 3RF23 ..-.D... |
| :---: | :---: | :---: | :---: | :---: | :---: |
| General data |  |  |  |  |  |
| Ambient temperature <br> - During operation, derating from $40^{\circ} \mathrm{C}$ <br> - During storage | $\begin{aligned} & { }^{\circ} \mathrm{C} \\ & { }^{\circ} \mathrm{C} \end{aligned}$ | $\begin{aligned} & -25 \ldots+60 \\ & -55 \ldots+80 \end{aligned}$ |  |  |  |
| Installation altitude | m | $0 . . .1000 ;$ der |  |  |  |
| Shock resistance acc. to IEC 60068-2-27 | $\mathrm{g} / \mathrm{ms}$ | 15/11 |  |  |  |
| Vibration resistance acc. to IEC 60068-2-6 | $g$ | 2 |  |  |  |
| Degree of protection |  | IP20 |  |  |  |
| Electromagnetic compatibility (EMC) |  |  |  |  |  |
| - Emitted interference acc. to IEC 60947-4-3 <br> - Conducted interference voltage <br> - Emitted, high-frequency interference voltage |  | Class A for ind | cations | Class A for industrial applications; <br> Class B for residential/ business/ commercial applications up to 16 A , AC51 Low Noise | Class A for industrial applications |
| - Interference immunity <br> - Electrostatic discharge acc. to IEC 61000-4-2 (corresponds to degree of severity 3 ) <br> - Induced RF fields acc. to IEC 61000-4-6 <br> - Burst acc. to IEC 61000-4-4 <br> - Surge acc. to IEC 61000-4-5 | kV <br> MHz <br> kV <br> kV | Contact disch <br> 0.15 ... 80; 14 <br> 2/5.0 kHz; beh Conductor - g | ischarge 8; beh <br> avior criterion 1 <br> on 1 <br> ductor - condu | n 2 <br> vior criterion 2 |  |


| Order No. |  | 3RF23 ..-1.... | 3RF23 ..-2.... | 3RF23 ..-3.... |
| :---: | :---: | :---: | :---: | :---: |
| General data |  |  |  |  |
| Connection type |  | (f) Screw terminals | OO Spring-type terminals | Ring terminal lug connections |
| Connection, main contacts <br> - Conductor cross-section <br> - Solid <br> - Finely stranded with end sleeve <br> - Finely stranded without end sleeve <br> - Solid or stranded, AWG cables <br> - Terminal screw <br> - Tightening torque <br> - Cable lug <br> - DIN <br> - JIS | $\mathrm{mm}^{2}$ <br> $\mathrm{mm}^{2}$ <br> $\mathrm{mm}^{2}$ <br> Nm <br> lb.in | $\begin{aligned} & \left.2 \times(1.5 \ldots 2.5)^{1}\right), 2 \times(2.5 \ldots 6)^{1)} \\ & 2 \times(1 \ldots 2.5)^{1)}, 2 \times(2.5 \ldots 6)^{1)}, \\ & 1 \times 10 \\ & - \\ & 2 \times(\text { AWG } 14 \ldots 10) \\ & \text { M4 } \\ & 2 \ldots 2.5 \\ & 7 \ldots 10.3 \end{aligned}$ | $\begin{aligned} & 2 x(0.5 \ldots 2.5) \\ & 2 x(0.5 \ldots 1.5) \\ & 2 \times(0.5 \ldots 2.5) \\ & 2 \times(\text { AWG } 18 \ldots 14) \end{aligned}$ | -- -- -- -- M5 2 ... 2.5 7 ... 10.3 DIN 46234 $-5-2.5,-5-6,-5-10,-5-16,-5-25$ JIS C 2805 R 2-5, 5.5-5, 8-5, 14-5 |
| Connection, auxiliary/control contacts <br> - Conductor cross-section <br> - Stripped length <br> - Terminal screw <br> - Tightening torque | mm <br> AWG <br> mm <br> Nm lb.in | $\begin{aligned} & \left.1 \times(0.5 \ldots 2.5)^{1}\right), 2 \times(0.5 \ldots 1.0) \\ & \text { AWG } 20 \ldots 12 \\ & 7 \\ & \text { M3 } \\ & 0.5 \ldots 0.6 \\ & 4.5 \ldots 5.3 \end{aligned}$ | 0.5 ... 2.5 AWG $20 \ldots 12$ 10 -- -- -- | $\begin{aligned} & 1 \times(0.5 \ldots 2.5), 2 \times(0.5 \ldots 1.0) \\ & \text { AWG } 20 \ldots 12 \\ & 7 \\ & \text { M3 } \\ & 0.5 \ldots 0.6 \\ & 4.5 \ldots 5.3 \end{aligned}$ |

## Permissible mounting positions



1) If two different conductor cross-sections are connected to one clamping point, both cross-sections must lie in the range specified. If identical cross-sections are used, this restriction does not apply.

| Type |  | 3RF23 ..-.... 2 | 3RF23 ..-... 4 | 3RF23 ..-... 5 | 3RF23 ..-.... 6 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Main circuit |  |  |  |  |  |
| Rated operational voltage $\mathbf{U}_{\mathbf{e}}$ | V | $24 . .230$ | 48 ... 460 | $48 \ldots 600$ | $48 \ldots 600$ |
| - Operating range | V | $20 . . .253$ | 40 ... 506 | 40 ... 660 | 40 ... 660 |
| - Rated frequency | Hz | $50 / 60 \pm 10$ \% |  |  |  |
| Rated insulation voltage $\boldsymbol{U}_{\mathbf{i}}$ | V | 600 |  |  |  |
| Blocking voltage | V | 800 | 1200 |  | 1600 |
| Rage of voltage rise | V/ $\mu \mathrm{s}$ | 1000 |  |  |  |


| Type |  | 3RF23 ..-... 0. | 3RF23 ..-..1. |  | 3RF23 ..-...2. | 3RF23 ..-...4. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Control circuit |  |  |  |  |  |  |
| Method of operation |  | DC operation | AC/DC operation |  | AC operation | DC operation |
| Rated control supply voltage $\boldsymbol{U}_{\text {s }}$ | V | $\begin{aligned} & 24 \text { DC acc. to } \\ & \text { EN 61131-2 } \end{aligned}$ | 24 AC | 24 DC | 110 ... 230 AC | 4 ... 30 DC |
| Rated frequency of the control supply voltage | Hz | -- | $\begin{aligned} & 50 / 60 \\ & \pm 10 \% \\ & \hline \end{aligned}$ | -- | 50/60 $\pm 10$ \% | -- |
| Actuating voltage, max. | V | 30 | 26.5 AC | 30 DC | 253 | 30 |
| Typical actuating current | mA | 20/Low Power: < $10^{1)}$ | 20 | 20 | 15 | 20 |
| Response voltage | V | 15 | 14 AC | 15 DC | 90 | 4 |
| Drop-out voltage | V | 5 | 5 AC | 55 DC | 40 | 1 |
| Operating times |  |  | 10 + max. one half-wave ${ }^{2)}$ |  |  |  |
| - ON-delay | ms | 1 + max. one half-wave ${ }^{2)}$ |  |  | $\begin{aligned} & 40+\text { max__ one }^{40} \\ & \text { half-wave } \end{aligned}$ | 1 + max. one half-wave ${ }^{2)}$ |
| - OFF-delay | ms | $1+\max$. one half-wave | 15 + max. one half-wave |  | 40 + max. one half-wave | $1+$ max. one half-wave |

1) Applies to the version "Low Power" 3RF23 ..-.AA..-OKNO.
2) Only for zero-point-switching devices.

## Solid-State Switching Devices for Resistive Loads

 Solid-State Contactors
## 3RF23 solid-state contactors, single-phase

| Order No. | Type current AC-51 ${ }^{1)}$ |  |  | Power loss at $I_{\text {max }}$ | Minimum load current | Leakage current | Rated impulse withstand capacity $I_{\text {tsm }}$ | $I^{2} t$ value |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | For $I_{\max }$ at $40^{\circ} \mathrm{C}$ | Acc. to IEC 60947-4-3 for $40^{\circ} \mathrm{C}$ | Acc. to UL/CSA for $50^{\circ} \mathrm{C}$ |  |  |  |  |  |
|  | A | A | A | W | A | mA | A | $A^{2} \mathrm{~S}$ |
| Main circuit |  |  |  |  |  |  |  |  |
| $\begin{aligned} & \text { 3RF23 1.-.A.. } 2 \\ & \text { 3RF23 1.-.A.. } 4 \\ & \text { 3RF23 1.-.A.. } 5 \\ & \text { 3RF23 1.-.A.. } 6 \end{aligned}$ | 10.5 | 7.5 | 9.6 | 11 | 0.1 | 10 | $\begin{aligned} & 200 \\ & 200 \\ & 200 \\ & 400 \end{aligned}$ | $\begin{aligned} & 200 \\ & 200 \\ & 200 \\ & 800 \end{aligned}$ |
| $\begin{aligned} & \hline \text { 3RF23 2.-.A.. } 2 \\ & \text { 3RF23 2.-.A.. } 4 \\ & \text { 3RF23 2.-... } 5 \\ & \text { 3RF23 2.-.A.. } 6 \\ & \text { 3RF23 2.-.C.. } \\ & \text { 3RF23 2.-.C.. } 4 \\ & \text { 3RF23 2.-.D.. } 2 \\ & \text { 3RF23 2.-.D.. } 4 \\ & \hline \end{aligned}$ | 20 | 13.2 | 17.6 | 20 | 0.5 | $\begin{aligned} & 10 \\ & 10 \\ & 10 \\ & 10 \\ & 25 \\ & 25 \\ & 10 \\ & 10 \end{aligned}$ | 600 600 600 600 600 600 1150 1150 | $\begin{aligned} & 1800 \\ & 1800 \\ & 1800 \\ & 1800 \\ & 1800 \\ & 1800 \\ & 6600 \\ & 6600 \end{aligned}$ |
| $\begin{aligned} & \text { 3RF23 3.-.A.. } 2 \\ & \text { 3RF23 3.-.... } 4 \\ & \text { 3RF23 3.-.A.. } 5 \\ & \text { 3RF23 3.-.A.. } 6 \\ & \text { 3RF23 3.-.C.. } 2 \\ & \text { 3RF23 3.-.D.. } \end{aligned}$ | 30 | 22 | 27 | 33 | 0.5 | $\begin{aligned} & \hline 10 \\ & 10 \\ & 10 \\ & 10 \\ & 25 \\ & 10 \end{aligned}$ | 600 <br> 600 <br> 600 <br> 600 <br> 600 <br> 1150 | $\begin{aligned} & \hline 1800 \\ & 1800 \\ & 1800 \\ & 1800 \\ & 1800 \\ & 6600 \end{aligned}$ |
| $\begin{aligned} & \text { 3RF23 4.-.A.. } 2 \\ & \text { 3RF23 4.-.A.. } 4 \\ & \text { 3RF23 4.-.A.. } 5 \\ & \text { 3RF23 4.-.A.. } 6 \end{aligned}$ | 40 | 33 | 36 | 44 | 0.5 | 10 | $\begin{aligned} & 1200 \\ & 1200 \\ & 1200 \\ & 1150 \end{aligned}$ | $\begin{aligned} & \hline 7200 \\ & 7200 \\ & 7200 \\ & 6600 \end{aligned}$ |
| $\begin{aligned} & \text { 3RF23 5.-.A.. } 2 \\ & \text { 3RF23 5.-.A.. } 4 \\ & \text { 3RF23 5.-.A.. } 5 \\ & \text { 3RF23 5.-.A.. } 6 \end{aligned}$ | 50 | 36 | 45 | 54 | 0.5 | 10 | 1150 | 6600 |
| $\begin{aligned} & \text { 3RF23 7.-.A.. } 2 \\ & \text { 3RF23 7.-.A.. } 4 \\ & \text { 3RF23 7.-.A.. } 5 \\ & \text { 3RF23 7.-.A.. } 6 \end{aligned}$ | 70 | 70 | 62 | 83 | 0.5 | 10 | 1150 | 6600 |
| $\begin{aligned} & \text { 3RF23 9.-.A.. } 2 \\ & \text { 3RF23 9.-.A.. } 4 \\ & \text { 3RF23 9.-.A.. } 5 \\ & \text { 3RF23 9.-.A.. } 6 \end{aligned}$ | 88 | 88 | 80 | 117 | 0.5 | 10 | 1150 | 6600 |

1) The type current provides information about the performance of the solidstate contactor. The actual permitted rated operational current $I_{\mathrm{e}}$ can be smaller depending on the connection method and start-up conditions.
For derating see the characteristic curves on page 30.

| Order No. | Type current AC-51 ${ }^{1)}$ |  |  | Type current AC-15 |  | Power loss at $I_{\text {max }}$ | Minimum load current | Leakage current | Rated impulse withstand capacity $I_{\text {tsm }}$ | $I^{2} t$ value |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | For $I_{\text {max }}$ at $40^{\circ} \mathrm{C}$ | Acc. to IEC 60947-4-3 for $40^{\circ} \mathrm{C}$ | Acc. to UL/CSA for $50^{\circ} \mathrm{C}$ | $\begin{aligned} & 10 \times I_{\mathrm{e}} \\ & \text { for } \\ & 60 \mathrm{~ms} \end{aligned}$ | Parameters |  |  |  |  |  |
|  | A | A | A | A |  | W | A | mA | A | $A^{2} \mathrm{~S}$ |
| Main circuit |  |  |  |  |  |  |  |  |  |  |
| $\begin{aligned} & \text { 3RF23 1.-.B.. } 2 \\ & \text { 3RF23 1.-.B.. } 4 \\ & \text { 3RF23 1.-.B.. } 6 \end{aligned}$ | 10.5 | 7.5 | 9.6 | 6 | $\begin{aligned} & 1200 \text { 1/h } \\ & 50 \% \text { ON } \\ & \text { period } \\ & \hline \end{aligned}$ | 11 | 0.1 | 10 | $\begin{aligned} & 200 \\ & 200 \\ & 400 \end{aligned}$ | $\begin{aligned} & 200 \\ & 200 \\ & 800 \end{aligned}$ |
| $\begin{aligned} & \hline \text { 3RF23 2.-.B.. } 2 \\ & \text { 3RF23 2.-.B.. } 4 \\ & \text { 3RF23 2.-.B.. } 6 \end{aligned}$ | 20 | 13.2 | 17.6 | 12 | $\begin{aligned} & 1200 \text { 1/h } \\ & 50 \% \text { ON } \\ & \text { period } \\ & \hline \end{aligned}$ | 20 | 0.5 | 10 | 600 | 1800 |
| $\begin{aligned} & \hline \text { 3RF23 3.-B.. } 2 \\ & \text { 3RF23 3..... } 4 \\ & \text { 3RF23 3.-.B.. } 6 \end{aligned}$ | 30 | 22 | 27 | 15 | $\begin{aligned} & 1200 \text { 1/h } \\ & 50 \% \text { ON } \\ & \text { period } \\ & \hline \end{aligned}$ | 33 | 0.5 | 10 | 600 | 1800 |
| $\begin{aligned} & \text { 3RF23 4.-.B.. } 2 \\ & \text { 3RF23 4.-.B.. } 4 \\ & \text { 3RF23 4.-.B.. } 6 \end{aligned}$ | 40 | 33 | 36 | 20 | $\begin{aligned} & 1200 \text { 1/h } \\ & 50 \% \text { ON } \\ & \text { period } \\ & \hline \end{aligned}$ | 44 | 0.5 | 10 | $\begin{aligned} & 1200 \\ & 1200 \\ & 1150 \\ & \hline \end{aligned}$ | $\begin{aligned} & 7200 \\ & 7200 \\ & 6600 \\ & \hline \end{aligned}$ |
| $\begin{aligned} & \text { 3RF23 5.-.B.. } 2 \\ & \text { 3RF23 5.-.B.. } 4 \\ & \text { 3RF23 5.-.B.. } 6 \end{aligned}$ | 50 | 36 | 45 | 25 | $\begin{aligned} & 1200 \text { 1/h } \\ & 50 \% \text { ON } \\ & \text { period } \end{aligned}$ | 54 | 0.5 | 10 | 1150 | 6600 |
| 3RF23 7.-.B.. 2 3RF23 7.-.B.. 4 3RF23 7.-.B.. 6 | 70 | 70 | 62 | 27.5 | $\begin{aligned} & 1200 \text { 1/h } \\ & 50 \% \text { ON } \\ & \text { period } \\ & \hline \end{aligned}$ | 83 | 0.5 | 10 | 1150 | 6600 |
| $\begin{aligned} & \hline \text { 3RF23 9.-.B.. } 2 \\ & \text { 3RF23 9.-.B.. } 4 \\ & \text { 3RF23 9.-.B.. } 6 \end{aligned}$ | 88 | 88 | 80 | 30 | $\begin{aligned} & 1200 \text { 1/h } \\ & 50 \% \text { ON } \\ & \text { period } \end{aligned}$ | 117 | 0.5 | 10 | 1150 | 6600 |

1) The type current provides information about the performance of the solidstate contactor. The actual permitted rated operational current $I_{\mathrm{e}}$ can be smaller depending on the connection method and start-up conditions.
For derating see the characteristic curves on page 30.

# Solid-State Switching Devices for Resistive Loads <br> Solid-State Contactors 

3RF23 solid-state contactors, single-phase
Fused version with semiconductor protection (similar to type of coordination "2")1)

The semiconductor protection for the SIRIUS controls can be used with different protective devices. This allows protection by means of LV HRC fuses of gG operational class or miniature circuit breakers. Siemens recommends the use of special SITOR semiconductor fuses. The table below lists the maximum permissible fuses for each SIRIUS control.

If a fuse is used with a higher rated current than specified, semiconductor protection is no longer guaranteed. However, smaller fuses with a lower rated current for the load can be used without problems.
For protective devices with gG operational class and for SITOR 3NE1 all-range fuses, the minimum cross-sections for the conductor to be connected must be taken into account.

| Order No. | All-range fuses <br> LV HRC design gR/SITOR <br> 3NE1 | Cylindrical design gR/NEOZED ${ }^{2)}$ <br> SILIZED <br> 5SE1 | Semiconductor fuses/partial-range fuses |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | LV HRC design aR/SITOR <br> 3NE8 | Cylindrical design aR/SITOR <br> $10 \mathrm{~mm} \times 38 \mathrm{~mm}$ 3NC1 0 | aR/SITOR <br> $14 \mathrm{~mm} \times 51 \mathrm{~mm}$ 3NC1 4 | aR/SITOR <br> $22 \mathrm{~mm} \times 58 \mathrm{~mm}$ 3NC2 2 |
| 3RF23 1.-..... | 3NE1813-0 | 5SE1 316 | 3NE8 015-1 | 3NC1 010 | 3NC1 410 | 3NC2 220 |
| 3RF23 2.-..... | 3NE1814-0 | 5SE1 325 | 3NE8 015-1 | 3NC1 020 | 3NC1 420 | 3NC2 220 |
| 3RF23 3.-..... | 3NE1803-0 | 5SE1 335 | 3NE8 003-1 | 3NC1 032 | 3NC1 432 | 3NC2 232 |
| 3RF23 4.-..... | 3NE1802-0 | 5SE1 350 | 3NE8 017-1 | -- | 3NC1 440 | 3NC2 240 |
| 3RF23 5.-..... | 3NE1817-0 | 5SE1 363 | 3NE8 018-1 | -- | 3NC1 450 | 3NC2 250 |
| 3RF23 7.-.... 2 | 3NE1820-0 | -- | 3NE8 020-1 | -- | -- | 3NC2 280 |
| 3RF23 7.-... 4 | 3NE1020-2 | -- | 3NE8 020-1 | -- | -- | 3NC2 280 |
| 3RF23 7.-....53) | 3NE1020-2 | -- | 3NE8 020-1 | -- | -- | 3NC2 280 |
| 3RF23 7.-.... 6 | 3NE1020-2 | -- | 3NE8 020-1 | -- | -- | 3NC2 280 |
| 3RF23 9.-.... 2 | 3NE1021-2 | -- | 3NE8 021-1 | -- | -- | 3NC2 200 |
| 3RF23 9.-... 4 | 3NE1021-2 | -- | 3NE8 021-1 | -- | -- | 3NC2 2804) |
| 3RF23 9.-....5 ${ }^{3)}$ | 3NE1021-2 | -- | 3NE8 021-1 | -- | -- | 3NC2 2804) |
| 3RF23 9.-.... 6 | 3NE1020-24) | -- | 3NE8 021-1 | -- | -- | 3NC2 2804) |


| Order No. | Cable and line protection fuses |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | LV HRC design gG <br> 3NA6 | Cylindrical design gG <br> $10 \mathrm{~mm} \times 38 \mathrm{~mm}$ 3NW6 0 | gG <br> $14 \mathrm{~mm} \times 51 \mathrm{~mm}$ 3NW6 1 | $\begin{aligned} & \text { gG } \\ & 22 \mathrm{~mm} \times 58 \mathrm{~mm} \\ & \text { 3NW6 } 2 \end{aligned}$ | DIAZED quick $5 S B$ |
| 3RF23 1.-.... 2 3RF23 1.-... 4 3RF23 1.-...5) 3RF23 1.-... 6 | 3NA6 803 3NA6 801 3NA6 801 3NA6 803-6 | $\begin{aligned} & \text { 3NW6 001-14) } \\ & \text { 3NW6 001-14) } \\ & \text { 3NW6 001-14) } \end{aligned}$ | 3NW6 101-14) <br> 3NW6 101-14) <br> 3NW6 101-1 ${ }^{3}$ <br> -- | $\begin{aligned} & \text {-- } \\ & \text {-- } \end{aligned}$ | $\begin{aligned} & \text { 5SB1 } 41 \\ & \text { SSB1 41 } \\ & \text { 5SB1 } 41 \end{aligned}$ |
| $\begin{aligned} & \hline \text { 3RF23 2.-.... } 2 \\ & \text { 3RF23 2.-... } 4 \\ & \text { 3RF23 2.-...5 } \\ & \text { 3RF23 2.-... } 6 \\ & \hline \end{aligned}$ | 3NA6 807 3NA6 807 3NA6 807 3NA6 807-6 | 3NW6 007-1 ${ }^{4)}$ <br> 3NW6 005-1 ${ }^{4)}$ <br> 3NW6 005-1 ${ }^{4)}$ <br> -- | 3NW6 107-1 <br> 3NW6 105-14) <br> 3NW6 105-1 ${ }^{4)}$ <br> -- | 3NW6 207-1 <br> 3NW6 205-1 ${ }^{4}$ <br> 3NW6 205-1 ${ }^{\text {4) }}$ | $\begin{aligned} & \text { 5SB1 } 71 \\ & \text { 5SB1 } 71 \\ & \text { 5SB1 } 71 \end{aligned}$ |
| $\begin{aligned} & \text { 3RF23 3.-.... } 2 \\ & \text { 3RF23 3.-... } 4 \\ & \text { 3RF23 3.-...5 } \\ & \text { 3RF23 3.-... } 6 \end{aligned}$ | $\begin{aligned} & \text { 3NA6 } 810^{4)} \\ & \text { 3NA6 } 807^{4)} \\ & \text { 3NA6 } 807^{4)} \\ & \text { 3NA6 } 807-6^{4)} \\ & \hline \end{aligned}$ |  | 3NW6 107-14) <br> 3NW6 105-14) <br> 3NW6 105-1 ${ }^{4)}$ <br> -- | 3NW6 207-1 <br> 3NW6 205-14) <br> 3NW6 205-1 ${ }^{\text {4) }}$ <br> -- | $\begin{aligned} & \text { 5SB3 } 11 \\ & \text { 5SB3 } 11 \\ & \text { 5SB3 } 11 \end{aligned}$ |
| $\begin{aligned} & \hline \text { 3RF23 4.-.... } 2 \\ & \text { 3RF23 4.-... } 4 \\ & \text { 3RF23 4.-...5) } \\ & \text { 3RF23 4.-.... } 6 \end{aligned}$ | 3NA6 817 <br> 3NA6 $812^{4)}$ <br> 3NA6 $812^{4)}$ <br> -- | -- | 3NW6 117-1 <br> 3NW6 112-14 <br> 3NW6 112-14) <br> -- | 3NW6 217-1 <br> 3NW6 212-14) <br> 3NW6 212-1 ${ }^{4)}$ <br> -- | $\begin{aligned} & \text { 5SB3 } 21 \\ & \text { 5SB3 } 21 \\ & \text { 5SB3 } 21 \end{aligned}$ |
| $\begin{aligned} & \hline \text { 3RF23 5.-.... } 2 \\ & \text { 3RF23 5.-... } 4 \\ & \text { 3RF23 5.-...5 } \\ & \text { 3RF23 5.-... } 6 \end{aligned}$ |  | -- | -- | 3NW6 217-14) | $\begin{aligned} & \text { 5SB3 } 21 \\ & \text { 5SB3 } 21 \\ & \text { 5SB3 } 21 \end{aligned}$ |
| 3RF23 7.-.... 2 3RF23 7.-... 4 3RF23 7.-...5) 3RF23 7.-... 6 | -- | -- <br> -- <br> -- | $\begin{aligned} & \text {-- } \\ & \hline-- \end{aligned}$ | -- | $\begin{aligned} & \text { 5SB3 } 21^{4)} \\ & \text { 5SB3 } 21^{4} \\ & \text { 5SB3 } 21^{4)} \end{aligned}$ |
| $\begin{aligned} & \text { 3RF23 9.-.... } 2 \\ & \text { 3RF23 9.-... } 4 \\ & \text { 3RF23 9.-...5 } \\ & \text { 3RF23 9.-... } 6 \end{aligned}$ | -- -- -- | -- -- -- | -- -- -- | -- | $\begin{aligned} & \text { 5SB3 314) } \\ & \text { 5SB3 } 21^{4)} \\ & \text { 5SB3 } 21^{4)} \end{aligned}$ |

Suitable fuse holders, fuse bases and controls can be found in
Catalog LV 1, Chapter 19.

1) Type of coordination "2" according to EN 60947-4-1:

In the event of a short-circuit, the controls in the load feeder must not endanger persons or the installation. They must be suitable for further operation. For fused configurations, the protective device must be replaced.
2) For use only with operational voltage $U_{e}$ up to 400 V .
3) For use only with operational voltage $U_{e}$ up to 506 V .
4) These fuses have a smaller rated current than the solid-state contactors.

## Solid-State Switching Devices for Resistive Loads Solid-State Contactors

## 3RF23 solid-state contactors, single-phase

## Characteristic curves

Derating curves
For designation of the characteristic curves see page 32.


Type current 10.5 A (3RF23 10)


Type current 20 A (3RF23 20)


Type current 30 A (3RF23 30-.AA.., -.BA.., -.CA..)

## Solid－State Switching Devices for Resistive Loads <br> Solid－State Contactors

3RF23 solid－state contactors，single－phase



Type current 30 A（3RF23 30－．DA．．）


Type current 40 A（3RF23 40）${ }^{1)}$


Type current 50 A（3RF23 50）${ }^{1)}$

Note：When loaded with IIEC，the maximum overtemperature at the heat sink is 50 K ．

1）Identical current／temperature curves for stand－alone and side－by－side installation．

## Solid-State Switching Devices for Resistive Loads Solid-State Contactors

## 3RF23 solid-state contactors, single-phase



Type current $70 \mathrm{~A}(3 \mathrm{RF} 2370)^{1)}$


Type current 88 A (3RF23 90) ${ }^{1) 2}$ )


Note: When loaded with IIEC, the maximum overtemperature at the heat sink is 50 K .

## Mounting regulations



Clearances for stand-alone and side-by-side installation

1) Identical current/temperature curves for stand-alone and side-by-side installation.
2) $I_{\text {max }}$ and $I_{\text {IEC }}$ have identical curves.

# Solid-State Switching Devices for Resistive Loads <br> Solid-State Contactors 

3RF23 solid-state contactors, single-phase

## Dimensional drawings

Type current 10.5 A and 20 A


Type current 30 A


Type current 40 A and 50 A


## Solid-State Switching Devices for Resistive Loads

 Solid-State ContactorsType current 70 A


Type current 88 A


Terminal cover
3RF29 00-3PA88


Schematics
Version
DC control supply voltage


## Technical specifications



1) These products were built as Class A devices. The use of these devices in residential areas could result in lead in radio interference. In this case these may be required to introduce additional interference suppression measures.
2) If two different conductor cross-sections are connected to one clamping point, both cross-sections must lie in the range specified. If identical cross-sections are used, this restriction does not apply.

## Solid-State Switching Devices for Resistive Loads

 Solid-State Contactors
## 3RF24 solid-state contactors, three-phase

| Order No. | Type current | Rated operational current $I_{\text {e }}$ |  | Power loss at | Minimum load | Max. leakage | Rated impulse | $I^{2} t$ value |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $I_{\text {AC-51 }}$ <br> at $40^{\circ} \mathrm{C}$ | Acc. to IEC 60947-4-3 for $40^{\circ} \mathrm{C}$ | Acc. to UL/CSA for $50^{\circ} \mathrm{C}$ | $I_{\text {AC-51 }}$ |  |  | withstand capacity $I_{\text {tsm }}$ |  |
|  | A | A | A | W | A | mA | A | $A^{2} \mathrm{~S}$ |
| Main circuit |  |  |  |  |  |  |  |  |
| 3RF24 10-.AB. 5 | 10.5 | 7 | 7 | 23 | 0.1 | 10 | 200 | 200 |
| 3RF24 20-.AB. 5 | 22 | 15 | 15 | 44 | 0.5 | 10 | 600 | 1800 |
| 3RF24 30-.AB. 5 | 30 | 22 | 22 | 61 | 0.5 | 10 | 1200 | 7200 |
| 3RF24 40-.AB. 5 | 40 | 30 | 30 | 80 | 0.5 | 10 | 1150 | 6600 |
| 3RF24 50-.AB. 5 | 50 | 38 | 38 | 107 | 0.5 | 10 | 1150 | 6600 |
| 3RF24 10-.AC. 5 | 10.5 | 7 | 7 | 31 | 0.1 | 10 | 300 | 450 |
| 3RF24 20-.AC. 5 | 22 | 15 | 15 | 66 | 0.5 | 10 | 600 | 1800 |
| 3RF24 30-.AC. 5 | 30 | 22 | 22 | 91 | 0.5 | 10 | 1200 | 7200 |
| 3RF24 40-.AC. 5 | 40 | 30 | 30 | 121 | 0.5 | 10 | 1150 | 6600 |
| 3RF24 50-.AC. 5 | 50 | 38 | 38 | 160 | 0.5 | 10 | 1150 | 6600 |

1) The type current provides information about the performance of the solidstate contactor. The actual permitted rated operational current $I_{\mathrm{e}}$ can be smaller depending on the connection method and start-up conditions.
For derating see the characteristic curves on page 38.


Fused version with semiconductor protection (similar to type of coordination "2")1)

The semiconductor protection for the 3RF24 controls can be used with different protective devices. Siemens recommends the use of special SITOR semiconductor fuses. The table below lists the maximum permissible fuses for each 3RF24 control.

If a fuse is used with a higher rated current than specified, semiconductor protection is no longer guaranteed. However, smaller fuses with a lower rated current for the load can be used without problems.

| Order No. | All-range fuses |  | Semiconductor fuses/partial-range fuses |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | LV HRC design gR/SITOR <br> 3NE1 | Cylindrical design gR/NEOZED ${ }^{2)}$ <br> SILIZED 5SE1 | LV HRC design aR/SITOR 3NE8 | Cylindrical design aR/SITOR <br> $10 \mathrm{~mm} \times 38 \mathrm{~mm}$ 3NC1 0 | aR/SITOR <br> $14 \mathrm{~mm} \times 51 \mathrm{~mm}$ 3NC1 4 | aR/SITOR <br> $22 \mathrm{~mm} \times 58 \mathrm{~mm}$ 3NC2 2 |
| Operational voltage $\boldsymbol{U}_{\text {e }}$ up to 460 V (+10\%) |  |  |  |  |  |  |
| 3RF24 10-.A... | 3NE1 813-0 | 5SE1 310 | 3NE8 015-1 | 3NC1 012 | 3NC1 415 | 3NC2 220 |
| 3RF24 20-A... | 3NE1 814-0 | 5SE1 320 | 3NE8 015-1 | 3NC1 025 | 3NC1 425 | 3NC2 225 |
| 3RF24 30-.A... | 3NE1 803-0 | 5SE1 335 | 3NE8 003-1 | 3NC1 032 | 3NC1 432 | 3NC2 232 |
| 3RF24 40-.A... | 3NE1 802-0 | 5SE1 350 | 3NE8 017-1 | -- | 3NC1 450 | 3NC2 250 |
| 3RF24 50-.A... | 3NE1 817-0 | 5SE1 350 | 3NE8 018-1 | -- | 3NC1 450 | 3NC2 263 |
| Operational voltage $\boldsymbol{U}_{\text {e }}$ up to 600 V (+10\%) |  |  |  |  |  |  |
| 3RF24 10-.A... | 3NE1 813-0 | -- | 3NE8 015-1 | 3NC1 012 | 3NC1 415 | 3NC2 220 |
| 3RF24 20-. ${ }^{\text {a }}$.. | 3NE1 814-0 | -- | 3NE8 015-1 | 3NC1 025 | 3NC1 425 | 3NC2 225 |
| 3RF24 30-A... | 3NE1 803-0 | -- | 3NE8 003-1 | 3NC1 032 | 3NC1 432 | 3NC2 232 |
| 3RF24 40-.A... | 3NE1 802-0 | -- | 3NE8 017-1 | -- | 3NC1 450 | 3NC2 250 |
| 3RF24 50-.A... | 3NE1 817-0 | -- | 3NE8 018-1 | -- | 3NC1 450 | 3NC2 263 |


| Order No. | Cable and line protection fuses |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | LV HRC design gG 3NA6 | Cylindrical desig gG $10 \mathrm{~mm} \times 38 \mathrm{~mm}$ 3NW6 0 | gG <br> $14 \mathrm{~mm} \times 51 \mathrm{~mm}$ 3NW6 1 | $\begin{aligned} & \text { gG } \\ & 22 \mathrm{~mm} \times 58 \mathrm{~mm} \\ & \text { 3NW6 } 2 \end{aligned}$ | DIAZED quick $5 \mathrm{SB}$ |
| Operational voltage $U_{\text {e }}$ up to 460 V (+10\%) |  |  |  |  |  |
| $\begin{aligned} & \text { 3RF24 10-.AB.. } \\ & \text { 3RF24 10-.AC.. } \end{aligned}$ | $\begin{aligned} & \text { 3NA3 } 8013) \\ & \text { 3NA3 } 803 \end{aligned}$ | $\begin{aligned} & \text { 3NW6 001-13) } \\ & \text { 3NW6 001-13) } \end{aligned}$ | $\begin{aligned} & \text { 3NW6 101-13) } \\ & \text { 3NW6 101-13) } \end{aligned}$ | -- | $\begin{aligned} & \text { 5SB1 313) } \\ & \text { 5SB1 61 } \end{aligned}$ |
| 3RF24 20-.A... | 3NA3 805 ${ }^{3}$ | 3NW6 005-1 ${ }^{3)}$ | 3NW6 105-1 ${ }^{3)}$ | 3NW6 205-13) | 5SB1 81 |
| 3RF24 30-.A... | 3NA3 812 | -- | 3NW6 112-1 | -- | 5SB3 11 |
| 3RF24 40-.A... | 3NA3 812 ${ }^{3)}$ | -- | 3NW6 112-13) | 3NW6 210-1 ${ }^{3}$ | 5SB3 21 |
| 3RF24 50-.A... | 3NA3 812 ${ }^{3)}$ | -- | -- | 3NW6 210-1 ${ }^{3}$ | 5SB3 21 ${ }^{3}$ |

Suitable fuse holders, fuse bases and controls can be found in
Catalog LV 1, Chapter 19.

1) Type of coordination "2" according to EN 60947-4-1:

In the event of a short-circuit, the controls in the load feeder must not endanger persons or the installation. They must be suitable for further operation. For fused configurations, the protective device must be replaced.
2) For use only with operational voltage $U_{e}$ up to 400 V .
3) These fuses have a smaller rated current than the solid-state contactors.

## Solid-State Switching Devices for Resistive Loads Solid-State Contactors

## 3RF24 solid-state contactors, three-phase

## Characteristic curves

Derating curves, two-phase controlled


Type current 10.5 A (3RF24 10-.AB..)


Type current 20 A (3RF24 20-. AB ..)


Type current 30 A (3RF24 30-. AB..)

## Solid-State Switching Devices for Resistive Loads <br> Solid-State Contactors

3RF24 solid-state contactors, three-phase


Type current 40 A (3RF24 40-.AB..) ${ }^{1)}$


Type current 50 A (3RF24 50-.AB..) ${ }^{1)}$

|  | $I_{\text {max }}$ Thermal limit current for individual mounting |
| :---: | :---: |
|  | $I_{\text {max }}$ Thermal limit current for side-by-side mounting |
|  | $I_{\text {IEC }}$ Current acc. to IEC 947-4-3 for individual mounting |
|  | $I_{\text {IEC }}$ Current acc. to IEC 947-4-3 for side-by-side mounting |

Note: When loaded with IIEC, the maximum overtemperature at the heat sink is 50 K .

## Mounting regulations



Clearances for stand-alone and side-by-side installation

1) Identical current/temperature curves for stand-alone and side-by-side installation.

## Solid-State Switching Devices for Resistive Loads Solid-State Contactors

## 3RF24 solid-state contactors, three-phase

Derating curves, three-phase controlled


Type current 10.5 A (3RF24 10-.AC..)


Type current 20 A (3RF24 20-.AC..)


Type current 30 A (3RF24 30-.AC.. $)^{1)}$

1) Identical current/temperature curves for stand-alone and side-by-side installation.

## Solid-State Switching Devices for Resistive Loads <br> Solid-State Contactors

3RF24 solid-state contactors, three-phase


Type current 40 A (3RF24 40-.AC.. $)^{1)}$


Type current 50 A (3RF24 50-.AC.. $)^{1)}$
_ $I_{\text {max }}$ Thermal limit current for individual mounting $I_{\text {max }}$ Thermal limit current for side-by-side mounting
_ _ - $\quad I_{\text {IEC }}$ Current acc. to IEC 947-4-3 for individual mounting

Mounting regulations


Note: When loaded with IIEC, the maximum overtemperature at the heat sink is 50 K .

Clearances for stand-alone and side-by-side installation

1) Identical current/temperature curves for stand-alone and side-by-side installation.

Solid-State Switching Devices for Resistive Loads Solid-State Contactors

3RF24 solid-state contactors, three-phase

## Dimensional drawings

Type current 10.5 A


Type current $20 \mathrm{~A} ; 30 \mathrm{~A}$ (two-phase controlled)


# Solid-State Switching Devices for Resistive Loads <br> Solid-State Contactors 

3RF24 solid-state contactors, three-phase
Type current 30 A (three-phase controlled); $40 \mathrm{~A}, 50 \mathrm{~A}$

Screw terminal
3RF24 .0-1....


Ring terminal lug connection 3RF24 50-3....


|  | a | b | d | e |
| :--- | :---: | :---: | :---: | :---: |
| 3RF2430-.AC.. <br> 3RF2440-.AB.. | 100 | 113,5 | 100 | 85 |
| 3RF2440-.AC.. <br> 3RF2450-.AB.. | 100 | 157,5 | 146 | 80 |
| 3RF2450-.AC.. | 180 | 157,5 | 146 | 160 |

## Schematics

Two-phase controlled,
DC control supply voltage


Two-phase controlled,
AC control supply voltage


Three-phase controlled
DC control supply voltage


Three-phase controlled,
AC control supply voltage


## Solid-State Switching Devices for Resistive Loads

## 3RF29 Function Modules

## General data

## Overview

Function modules for SIRIUS 3RF2 solid-state switching devices
A great variety of applications demand an expanded range of functionality. With our function modules, these requirements can be met really easily. The modules are mounted simply by clicking them into place; straight away the necessary connections are made with the solid-state relay or contactor. The plug-in connection to control the solid-state switching devices can simply remain in use.

The following function modules are available:

- Converters
- Load monitoring
- Heating current monitoring
- Power controllers
- Power regulators

With the exception of the converter, the function modules can be used only with single-phase solid-state switching devices.

Technical specifications

| Type |  | 3RF29 ..-.E... | 3RF29 ..-.F... | 3RF29 ..-.G... | 3RF29 ..-.H... | 3RF29 ..-.J... | 3RF29 ..-.K... |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| General data |  |  |  |  |  |  |  |
| Ambient temperature |  |  |  |  |  |  |  |
| - During operation, derating from $40^{\circ} \mathrm{C}$ |  | $-25 \ldots+60$ |  |  |  |  |  |
| - During storage | ${ }^{\circ} \mathrm{C}$ | $-55 \ldots+80$ |  |  |  |  |  |
| Installation altitude | m | 0 ... 1000; derating from 1000 |  |  |  |  |  |
| Shock resistance acc. to IEC 60068-2-27 | $\mathrm{g} / \mathrm{ms}$ | 15/11 |  |  |  |  |  |
| Vibration resistance acc. to IEC 60068-2-6 | $g$ | 2 |  |  |  |  |  |
| Degree of protection |  | IP20 |  |  |  |  |  |
| Electromagnetic compatibility (EMC) |  |  |  |  |  |  |  |
| - Emitted interference <br> - Conducted interference voltage acc. to IEC 60947-4-3 <br> - Emitted, high-frequency interference voltage acc. to IEC 60947-4-3 |  | Class A for industrial applications |  |  |  |  |  |
| - Interference immunity <br> - Electrostatic discharge acc. to IEC 61000-4-2 (corresponds to degree of severity 3) <br> - Induced RF fields acc. to IEC 61000-4-6 <br> - Burst acc. to IEC 61000-4-4 <br> - Surge acc. to IEC 61000-4-5 | kV <br> MHz <br> kV | Contact disch $0.15 \ldots 80 ; 140$ <br> 2 kV/5.0 kHz; Conductor-g | 4; air dischar <br> B V ; behavior <br> avior criterion <br> nd 2; conducto | 8; behavior crite <br> rion 1 <br> conductor 1; be | n 2 <br> vior criterion 2 |  |  |
| Connection, auxiliary/control contacts, screw terminals |  |  |  |  |  |  |  |
| - Conductor cross-section | $\mathrm{mm}^{2}$ | $1 \times(0.5 \ldots 2.5), 2 \times(0.5 \ldots 1.0), 1 \times($ AWG $20 \ldots 12)$ |  |  |  |  |  |
| - Stripped length | mm |  |  |  |  |  |  |
| - Terminal screw |  | M3 |  |  |  |  |  |
| - Tightening torque | Nm $\mathrm{lb} . \mathrm{in}$ | $\begin{aligned} & 0.5 \ldots 0.6 \\ & 4.5 \ldots 5.3 \end{aligned}$ |  |  |  |  |  |
| Converter, feed-through opening <br> - Diameter | mm | -- | 7 | 17 |  |  |  |

1) Note limitations for power controller function modules. These modules were built as Class A devices. The use of these devices in residential areas could result in lead in radio interference. In this case these may be required to introduce additional interference suppression measures.

| Type |  | 3RF29 ..-.E.. 8 | 3RF29 ..-.F.. 8 | 3RF29 ..-.G.. 3 | 3RF29 ..-G.. 6 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Main circuit |  |  |  |  |  |
| Rated operational voltage $\boldsymbol{U}_{\mathrm{e}}$ <br> - Operating range <br> - Rated frequency | $\begin{aligned} & \mathrm{V} \\ & \mathrm{~V} \\ & \mathrm{~Hz} \end{aligned}$ | $\begin{aligned} & --1) \\ & -- \\ & -- \end{aligned}$ |  | $\begin{aligned} & 110 \ldots 230 \\ & 93.5 \ldots 253 \\ & 50 / 60 \end{aligned}$ | $\begin{aligned} & 400 \ldots 600 \\ & 340 \ldots 660 \end{aligned}$ |
| Rated insulation voltage $\boldsymbol{U}_{\mathrm{i}}$ | V | -- |  | 600 |  |
| Voltage measuring <br> - Measuring range | V | -- |  | 93.5 ... 253 | $340 \ldots 660$ |
| Mains voltage, fluctuation compensation | \% | -- |  | 20 |  |

1) Versions are independent of the main circuit.


## 3RF29 Function Modules

## Converters

## Overview

Converters for 3RF2 solid-state switching devices
These modules are used to convert analog control signals, such as those output from many temperature controllers for example, into a pulse-width-modulated digital signal. The connected so-lid-state contactors and relays can therefore regulate the output of a load as a percentage.

## Design

## Mounting

Easy snapping onto the 3RF21/3RF22 solid-state relays or 3RF23/3RF24 solid-state contactors establishes the connections to the solid-state switching devices. The connector on the solidstate switching devices from the control circuit can be plugged onto the converter without rewiring.

## Function

The analog value from a temperature controller is present at the $0 \ldots 10 \mathrm{~V}$ terminals. This controls the on-to-off period, as a function of voltage. The period duration is predefined at one second. Conversion of the analog voltage is linear in the voltage range from 0.1 ... 9.9 V. At voltages below approx. 0.1 V the connected switching device is not activated, while at voltages above approx. 9.9 V the connected switching device is always activated.

## Overview

## Load monitoring for 3RF2 single-phase solid-state switching devices

Many faults can be quickly detected by monitoring a load circuit connected to the solid-state switching device, as made possible with this module. Examples include the failure of load elements (up to 6 in the basic version or up to 12 in the extended version), alloyed power semiconductors, a lack of voltage or a break in a load circuit. A fault is indicated by one or more LEDs and reported to the controller by way of a PLC-compatible output.
The principle of operation is based on permanent monitoring of the current strength. This figure is continuously compared with the reference value stored once during commissioning by the simple press of a button. In order to detect the failure of one of several loads, the current difference must be $1 / 6$ (in the basic version) or $1 / 12$ (in the extended version) of the reference value. In the event of a fault, an output is actuated and one or more LEDs indicate the fault.

## Design

## Mounting

Easy snapping onto the 3RF21 solid-state relays or 3RF23 solidstate contactors establishes the connections to the solid-state switching devices. Because of the special design, the straightthrough transformer of the load monitoring module covers the lower main circuit connection. The cable to the load is simply pushed through and secured with the terminal screw.

## Function

The function module is activated when an "ON" signal is applied (IN terminal). The module constantly monitors the current level and compares this with the setpoint value.

## Startup

Pressing the Teach button or actuating the input IN2 switches the device on; the current through the solid-state switching device is detected and is stored as the setpoint value. During this process the two lower (red ${ }^{1)}$ ) LEDs flash alternately; simultaneous continuous light from the $3\left(\right.$ red $^{1}$ ) LEDs indicates the conclusion of the teaching process.
The Teach button can also be used to switch on the connected solid-state switching device briefly for test purposes. In this case the "ON" LED is switched on.

## Load monitoring

## Partial load faults, "Basic" load monitoring

If a deviation of at least $1 / 6$ of the stored setpoint value is detected, a fault is signaled. The fault is indicated by a "Fault" LED and by activation of the fault signaling output.

| LEDs | OK | Fault <br> Partial load <br> failurel <br> load short- <br> circuit | Thyristor defect | Mains failure/ <br> Fuse rupture |
| :--- | :--- | :--- | :--- | :--- | :--- |
| ON/OFF | $\checkmark$ | $\checkmark$ | -- | $\checkmark$ |
| Current <br> flowing | $\checkmark$ | $\checkmark$ | $\checkmark$ | -- |
| Group fault | -- | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| $\checkmark$ LED is lit |  |  |  |  |
| - LED is not lit |  |  |  |  |
| Partial load faults, "Extended" load monitoring |  |  |  |  |

Depending on the setting of the "response time" potentiometer, a deviation of at least $1 / 12$ of the stored setpoint value after a response time of between 100 ms and 3 s is signaled as a fault. The fault is indicated by a "Load" LED and by activation of the fault signaling output.
The potentiometer can also be used to determine the response behavior of the fault signaling output. When delay values are set in the left-hand half, the fault signal is stored. This can only be reset by switching on and off by means of the control supply voltage.
When settings are made on the right-hand side, the fault output is automatically reset after the deviation has been corrected.

## Voltage compensation, "Extended" load monitoring

In addition to the current, the load voltage is also detected. This makes it possible to compensate for influences on the current strength resulting from voltage fluctuations.

## Thyristor fault

If a current greater than the leakage current of the controls is measured in the deenergized state, the device triggers a thyristor fault after the set delay time. This means that the fault output is activated and the "Fault" ("Thyristor"1) LED lights up.

## Power system fault

If no current is measured in the energized state, the device triggers a power system fault after the set delay time. This means that the fault output is activated and the "Fault" ("Supply" ${ }^{11}$ ) LED lights up.

[^1]
## Solid-State Switching Devices for Resistive Loads

3RF29 Function Modules
Heating current monitoring

## Overview

Heating current monitoring for 3RF2 single-phase solidstate switching devices
Many faults can be quickly detected by monitoring a load circuit connected to the solid-state switching device, as made possible with this module. Examples include the failure of up to 6 load elements, alloyed power semiconductors, a lack of voltage or a break in a load circuit. A fault is indicated by LEDs and reported to the controller by way of a relay output (NC contact).
The principle of operation is based on permanent monitoring of the current strength. This figure is continuously compared with the reference value stored once during commissioning. In order to detect the failure of one of several loads, the current difference must be $1 / 6$ of the reference value. In the event of a fault, an output is actuated and the LEDs indicate the fault.
The heating current monitoring has a teach input and therefore differs from the load monitoring. This remote teaching function enables simple adjustment to changing loads without manual intervention.

## Design

## Mounting

Easy snapping onto the 3RF21 solid-state relays or 3RF23 solidstate contactors establishes the connections to the solid-state switching devices. Because of the special design, the straightthrough transformer of the heating current monitoring module covers the lower main circuit connection. The cable to the load is simply pushed through and secured with the terminal screw.

## Function

The function module is activated when an "ON" signal is applied (IN1 terminal). The module constantly monitors the current level and compares this with the setpoint value.

## Startup

Actuating the input IN2 switches the device on; the current through the solid-state switching device is detected and is stored as the setpoint value. During this process the two lower (red) LEDs flash alternately; simultaneous continuous light from the 3 (red) LEDs indicates the conclusion of the teaching process.

## Partial load faults

Depending on the setting of the "response time" potentiometer, a deviation of at least $1 / 6$ of the stored setpoint value after a response time of between 100 ms and 3 s is signaled as a fault. The fault is indicated by a "Load" LED and by activation of the fault signaling output.
The potentiometer can also be used to determine the response behavior of the fault signaling output. When delay values are set in the left-hand half, the fault signal is stored. This can only be reset by switching on and off by means of the control supply voltage.
When settings are made on the right-hand side, the fault output is automatically reset after the deviation has been corrected.

## Voltage compensation

In addition to the current, the load voltage is also detected. This makes it possible to compensate for influences on the current strength resulting from voltage fluctuations.

## Thyristor fault

If a current greater than the leakage current of the controls is measured in the deenergized state, the device triggers a thyristor fault after the set delay time. The fault output is activated and the "Thyristor" LED lights up.

## Power system fault

If no current is measured in the energized state, the device triggers a power system fault after the set delay time. The fault output is activated and the "Supply" LED lights up.

# Solid-State Switching Devices for Resistive Loads 3RF29 Function Modules 

## Power controllers

## Overview

## Power controllers for 3RF2 single-phase solid-state switching devices

The power controller is a function module for the autonomous power control of complex heating systems and inductive loads, for the operation of loads with temperature-dependent resistors and for simple indirect control of temperature.
The power controller can be used on the instantaneously switching 3RF21 and 3RF23 solid-state switching devices (singlephase). If only the full-wave operating mode is used, the power controller can also be used on the "zero-point switching" solidstate relays and contactors.
The following functions have been integrated:

- Power controller for adjusting the power of the connected load. Here, the setpoint value is set with a rotary knob on the module as a percentage with reference to the $100 \%$ power stored as a setpoint value.
- Inrush current limitation: With the aid of an adjustable voltage ramp, the inrush current is limited by means of phase control. This is useful above all with loads such as lamps or infrared lamps which have an inrush transient current.
- Load circuit monitoring for detecting load failure, partial load faults, alloyed power semiconductors, lack of voltage or a break in the load circuit.


## Special versions

## 3RF29 04-OKA13-0KC0

During the Teaching process the connected solid-state relay or contactor is not activated; i. e. no current flow takes place. No current reference value is stored. No part-load monitoring!

3RF29 ..-OKA1.-OKT0
No part-load monitoring!

## Design

## Mounting

Easy snapping onto the 3RF21 solid-state relays or 3RF23 solidstate contactors establishes the connections to the solid-state switching devices. Because of the special design, the straightthrough transformer of the function module covers the lower main circuit connection. The cable to the load is simply pushed through and secured with the terminal screw.

## Function

## Power control

The power controller sets the load current of the solid-state switching device depending on a setpoint value as a percentage. It does not compensate for changes in the mains voltage or load resistance. The modulation, the On/Off ratio or the phase angle, remains unchanged according to the setpoint value. The autonomous power control is performed between 0 and $100 \%$ of the setpoint selection.

## Full-wave control

If the left potentiometer $t_{\mathrm{R}}$ is set to 0 s (= far left), then the power controller operates according to the principle of full-wave control. The power set, be it internal or external, is converted into a pulse-width-modulated digital signal. The power controller controls the On and Off time of the solid-state switching device within a fixed period duration of 1 s so that the selected power is applied to the load. The "ON" LED flashes in the same rhythm as the solid-state switching device switches on and off.

## Generalized phase control

If the left potentiometer $t_{\mathrm{R}}$ is set to greater than 0 s , then the power controller operates according to the principle of generalized phase control.

In order to observe the limit values of the conducted interference voltage for industrial networks, the load circuit must include a reactor with a rating of at least $200 \mu \mathrm{H}$.

For SIDAC reactors for generalized phase control mode see page 50.

## Setpoint selection

The setpoint selection is set either internally with the right-hand potentiometer P to $0 \ldots 100 \%$ on the module or externally using the analog input $0 \ldots 10 \mathrm{~V}$.
In the case of full-wave control, $100 \%$ corresponds to continuously On and, in the case of generalized phase control, to a conduction angle of $180^{\circ}$ - and therefore maximum output.


Input characteristic

## Internal setpoint selection

In the case of internal setpoint selection, the module is controlled over the IN terminal. Terminal 10 has no function.

## External setpoint selection

With external setpoint selection (potentiometer $P$ far left $=0 \%$ ) the module is actuated by applying the analog voltage $0 \ldots 10 \mathrm{~V}$. $0 . . .10 \mathrm{~V}$ corresponds to $0 \ldots 100 \%$ power. Conversion of the voltage is linear between 0.1 and 9.9 V . Below 0.1 V the switching device remains off; at voltages above 9.9 V the power is always set to 100 \%.

## Inrush current limitation

The ramp time ( $t_{R}$ ) for a voltage ramp on switching on is set with the left potentiometer for the purpose of inrush current limitation. The set time refers to a power of $100 \%$. If, for example, a ramp time of 10 s is set and the power setpoint selection is $60 \%$, then the power of $60 \%$ will be reached after approx. 6 s .

## Line, load and thyristor monitoring

The power controller identifies partial load faults, mains failure and thyristor faults. The faults are indicated by the LEDs on the module and the fault output is actuated. The reference for the load monitoring is the taught value. A maximum of 6 partial loads can be monitored.

The response delay in the event of a fault amounts to approx.
100 ms in the case of full-wave control. In the case of generalized phase control and setpoint values > $50 \%$ the response delay amounts to 500 ms from the end of the ramp time.
The detection of partial load faults takes place only in the control range from 20 ... $100 \%$.

# Solid-State Switching Devices for Resistive Loads <br> 3RF29 Function Modules 

## Power regulators

## Overview

Power regulators for 3RF2 single-phase solid-state switching devices

The power regulator is a function module for the autonomous power control of complex heating systems, for the operation of loads with temperature-dependent resistors and for simple indirect control of temperature.

The power regulator can be used on the instantaneously switching 3RF21 and 3RF23 solid-state switching devices (singlephase). If only the full-wave operating mode is used, the power regulator can also be used on the zero-point-switching solidstate relays and contactors.
The following functions have been integrated:

- Power controller with proportional-action control for adjusting the power of the connected load. Here, the setpoint value is set with a rotary knob on the module as a percentage with reference to the 100 \% power stored as a setpoint value. Changes in the mains voltage or in the load resistance are compensated in this case.
- Inrush current limitation: With the aid of an adjustable voltage ramp, the inrush current is limited by means of phase control. This is useful above all with loads such as lamps which have an inrush transient current.
- Load circuit monitoring for detecting load failure, alloyed power semiconductors, lack of voltage or a break in the load circuit.


## Design

## Mounting

Easy snapping onto the 3RF21 solid-state relays or 3RF23 solidstate contactors establishes the connections to the solid-state switching devices. Because of the special design, the straightthrough transformer of the function module covers the lower main circuit connection. The cable to the load is simply pushed through and secured with the terminal screw.

## Function

## Power control

The power regulator adjusts the current in the connected load by means of a solid-state switching device depending on a setpoint value. Changes in the mains voltage or in the load resistance are thus compensated by the power regulator. The setpoint value can be predefined externally as a 0 to 10 V signal or internally by means of a potentiometer. Depending on the setting of the potentiometer ( $t_{\mathrm{R}}$ ), the adjustment is carried out according to the principle of full-wave control or generalized phase control.

## Full-wave control

In this operating mode the output is adjusted to the required setpoint value changing the on-to-off period. The period duration is predefined at one second.

## Generalized phase control

In this operating mode the output is adjusted to the required setpoint value by changing the current flow angle. The half-waves of the current are adjusted to produce the selected setpoint value of the power at the load.

In order to observe the limit values of the conducted interference voltage for industrial networks, the load circuit must include a reactor with a rating of at least $200 \mu \mathrm{H}$.

SIDAC reactors for generalized phase control mode

| Power control <br> regulators, power <br> regulators | Reactors <br> Rated voltage |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
| Type | Up to 230 V | Up to 480 V | Up to 660 V |
| 3RF2904-OKA. | 4EM4700-8CB00 | 4EM4915-0CB00 | 4EM5007-7CB00 |
| 3RF2920-0KA./-OHA. | 4EM4700-8CB00 | 4EM4915-0CB00 | 4EM5007-7CB00 |
| 3RF2950-0KA./-OHA. | 4EM5001-1CB00 | 4EM6100-6CB00 | 4EM6204-0CB00 |
| 3RF2990-0KA./-0HA. | 4EM6100-5CB00 | 4EM5316-7CB00 | 4EM5412-0CB00 |

## Setpoint selection

The setpoint selection is set either internally with the right-hand potentiometer P to $0 \ldots 100 \%$ on the module or externally using the analog input $0 \ldots 10 \mathrm{~V}$.

External setpoint selection
At $0 \%$ on the potentiometer the setpoint selection is set using an external $0 \ldots 10 \mathrm{~V}$ analog signal (terminals IN / $0 \ldots 10 \mathrm{~V}$ ). The device is switched on and off via the power supply (terminals A1/A2).

Internal setpoint selection
Above $0 \%$ the setpoint is set using the potentiometer. To allow this, the potential at terminal A1 must additionally be applied at the IN terminal. After removal of the "ON" signal, the switching module is switched off.

## Inrush current limitation

The ramp time ( $t_{R}$ ) for a voltage ramp on switching on is set with the left potentiometer for the purpose of inrush current limitation. If a time longer than 0 s is set, the device operates according to the generalized phase control principle. If 0 s is set, there is no voltage ramp and the device operates according to the principle of full-wave control.

## Load fault

If upon switching on with voltage applied the current flowing is not greater than the leakage current of the control, the device triggers a load fault. The fault relay is activated and the "Load" LED lights up.

## Thyristor fault

If a current greater than the leakage current of the control is measured in the deenergized state, the device triggers a thyristor fault. The fault relay is activated and the "Thyristor" LED lights up.

## Power system fault

If no current is measured in the energized state, the device triggers a power system fault. The fault relay is activated and the "Supply" LED lights up.

## Startup

Pressing the "Teach" button switches the device on; the current through the solid-state switching device and the mains voltage are detected and stored. The resultant output is taken as the 100 \% output for the setpoint selection. During this process the two lower red LEDs flash alternately. Simultaneous continuous light from the three red LEDs indicates the completion of the "Teach" process.

The "Teach" button can also be used to switch on the connected solid-state switching device briefly for test purposes. In this case the "ON" LED is switched on.

## Project planning aids

## Dimensional drawings

Converters
3RF29 00-0EA18

"Extended" load monitoring and heating current monitoring
3RF29 ..-0GA.. and -0JA..


Basic load monitoring
3RF29 ..-0FA08


Power controllers and regulators
3RF29 ..-OKA.., 3RF29 ..-OHA..


Schematics


Basic load monitoring


1) Internal connection.
2) Straight-through transformers.



Power controller and regulator

3) Voltage measuring not electrically isolated (3 $\mathrm{M} \Omega$ per path).

Solid-State Switching Devices for Resistive Loads 3RF29 Function Modules

## Project planning aids

## Switching examples

Converter


Extended load monitoring


1) Internal connection to the solid-state relay/contactor.
2) Straight-through transformer.
3) Make $\mathrm{PE} /$ ground connection according to installation regulations.
4) Connection of $\mathrm{L} / \mathrm{N}$ contact with:

3RF29 ..-0.A. 3 load monitoring/power controller
on neutral conductor N (e. g. 230 V ),
-3RF29 ..-0.A. 6 load monitoring/power controller on a second phase (e. g. 400 V ).

Basic load monitoring


Power controller and regulator

5) Voltage measuring not electrically isolated (3 $\mathrm{M} \Omega$ per path).
6) Grounding of connection L - is recommended.
7) A $200 \mu \mathrm{H}$ reactor must be used when operating with leading-edge phase in order to observe the limit values of the conducted interference voltage according to Class A.

# General data 



Solid-state contactors for switching motors
The solid-state contactors for switching motors are intended for frequently switching on and off three-phase current operating mechanisms up to 7.5 kW and reversing up to 3.0 kW . The devices are constructed with complete insulation and can be mounted directly on circuit breakers and SIRIUS overload relays, resulting in a very simple integration into motor feeders.
These three-phase solid-state contactors are equipped with a two-phase control which is particularly suitable for typical motor current circuits without connecting to the neutral conductor.
Important features:

- Insulated enclosure with integrated heat sink
- Degree of protection IP20
- Integrated mounting foot to snap on a standard mounting rail or for assembly onto a support plate
- Variety of connection methods
- Plug-in control connection
- Display via LEDs


## Selecting solid-state contactors

The solid-state contactors are selected on the basis of details of the network, the load and the ambient conditions. As the solidstate contactors are already equipped with an optimally matched heat sink, the selection process is considerably simpler than that for solid-state relays.
The following procedure is recommended:

- Determine the rated current of the load and the mains voltage
- Select a solid-state contactor with the same or higher rated current than the load
- Testing the maximum permissible switching frequency based on the characteristic curves (see pages 58 and 64). To do this, the starting current, the starting time and the motor loaded in in the operating phase must be known.
- If the permissible switching frequency is under the desired frequency, it is possible to achieve an increase by overdimensioning the motor!


## Design

## Load feeders

There is no typical design of a load feeder with solid-state relays or solid-state contactors; instead, the great variety of connection methods and control voltages offers universal application opportunities. SIRIUS solid-state relays and solid-state contactors can be installed in fuseless or fused feeders, as required. There are special versions with which it is even possible to achieve shortcircuit strength in a fuseless design.

## Mounting regulations



Clearances for stand-alone installation

## Connection methods

All SIRIUS solid-state switching devices are characterized by the great variance of connection methods. You can choose between the following connection methods:

## Screw connection

The screw connection system is the standard among industrial controls. Open terminals and a plus-minus screw are just two features of this technology. Two conductors of up to $6 \mathrm{~mm}^{2}$ can be connected in just one terminal. As a result, loads of up to 50 A can be connected.

## Spring-type terminals

This innovative technology manages without any screw connection. This means that very high vibration resistance is achieved. Two conductors of up to $2.5 \mathrm{~mm}^{2}$ can be connected to each terminal. As a result, loads of up to 20 A can be dealt with.

## General data

## Function

## Switching functions

The contactors to switch motors are "Instantaneous switching", because this method is particularly suited for inductive loads. By distributing the ON point over the entire sine curve of the mains voltage, disturbances are reduced to a minimum.

## Performance characteristics

The performance of the solid-state switching devices is substantially determined by the type of power semiconductors used and the internal design. In the case of the SIRIUS solid-state contactors and solid-state relays, only thyristors are used in place of less powerful Triacs.
Two of the most important features of thyristors are the blocking voltage and the maximum load integral:

## Blocking voltage

Thyristors with a high blocking voltage can also be operated without difficulty in networks with high interference voltages. Separate protective measures, such as a protective circuit with a varistor, are not necessary in most cases.
For example, for the SIRIUS solid-state switching devices e. g. thyristors with 800 V blocking voltage are built in for operation in networks up to 230 V . Thyristors with up to 1600 V are used for power systems with higher voltages.

## Maximum load integral

One of the purposes of specifying the maximum load integral $\left({ }^{\prime} t\right)$ is to determine the rating of the short-circuit protection. Only a large power semiconductor with a correspondingly high Rt value can be given appropriate protection against destruction from a short-circuit by means of a protective device matched to the application. However, the SIRIUS solid-state switching devices are also characterized by the optimum matching of the thyristors ( $R t$ value) to the rated currents. The rated currents specified on the devices according to EN 60947-4-3 were confirmed by extensive testing.
You can find more information on the Internet at:
http://www.siemens.com/cd/is_schalten/htm/_76/schalt.htm

## Integration

## Notes on integration in the load feeders

The SIRIUS solid-state switching devices are very easy to integrate into the load feeders thanks to their industrial connection method and design.
Particular attention must however be paid to the circumstances of the installation and ambient conditions, as the performance of the solid-state switching devices is largely dependent on these. Depending on the version, certain restrictions must be observed. Detailed information about the minimum spacing can be found in the technical specifications and the product data sheets.
Despite the rugged power semiconductors that are used, solidstate switching devices respond more sensitively to short-circuits in the load feeder. Consequently, special precautions have to be taken against destruction, depending on the type of design.
Siemens generally recommends using SITOR semiconductor fuses. These fuses also provide protection against destruction in the event of a short-circuit even when the solid-state contactors and solid-state relays are fully utilized.
Alternatively, if there is lower loading, protection can also be provided by standard fuses or miniature circuit breakers. This protection is achieved by overdimensioning the solid-state switching devices accordingly. The technical specifications and the product data sheets contain details both about the solid-state fuse protection itself and about use of the SIRIUS devices with conventional protection equipment.
Semiconductor motor and reversing contactors can be easily combined with the 3RV motor starter protectors and 3RB2 overload relay from the SIRIUS modular system. Thus, fuseless and fuse motor feeders can be designed easily and in a space-saving manner.
Note:
The operation of wye-connected three-phase induction motors (especially with ratings $<1 \mathrm{~kW}$ ) with electromechanical contactors can lead to very high EMC interference. Solid-state switching devices being used in the vicinity may be affected by this interference which lies above the permissible limit values.
In case of high EMC interference we recommend that motors up to 5.5 kW controlled by 3RT10 1. electromechanical contactors be equipped with EMC suppressor circuits. The best filtering effect is achieved with three-phase RC interference suppression modules such as 3RT19 16-1PA1 up to 400 V. Suitable modules for the contactors can be found in Chapter 3 under "Accessories and Spare Parts". Varistor interference suppression modules should not be used because they are unsatisfactory at filtering out rapid transients.

## Overview

These two-phase controlled, instantaneous switching solid-state contactors in the insulting enclosure are offered in 45 mm width to 5.2 A - and in 90 mm width to 16 A . This means that it is possible to operate motors up to 7.5 kW .

The devices can use a link module to directly connect to a circuit breaker. Direct mounting of a 3RB20 solid-state overload relay is also possible. Rapid-switching fuseless and fuse motor feeders can thereby be implemented in a time-saving manner.

Technical specifications


1) These products were built as Class A devices. The use of these devices in residential areas could result in lead in radio interference. In this case these may be required to introduce additional interference suppression measures.
2) If two different conductor cross-sections are connected to one clamping point, both cross-sections must lie in the range specified. If identical cross-sections are used, this restriction does not apply.

## Solid-State Switching Devices for Switching Motors

## Solid-State Contactors

## 3RF24 solid-state contactors, three-phase

| Order No. | Fuseless design with motor starter protector CLASS 10 |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Rated operational current $I_{\text {AC-53 }}{ }^{1)}$ acc. to IEC 60947-4-2 |  |  | Power loss at $I_{\text {AC-53 }}$ <br> at $40^{\circ} \mathrm{C}$ | Short-circuit protection with type of coordination "1" at an operational voltage of $U_{\mathrm{e}}$ to 440 V |  |  |  |
|  | at $40{ }^{\circ} \mathrm{C}$ | UL/CSA, at $50^{\circ} \mathrm{C}$ | at $60{ }^{\circ} \mathrm{C}$ |  | Motor starter protector |  | $I_{\text {q }}$ |  |
|  | A | A | A | W | Type |  | kA |  |
| Main circuit |  |  |  |  |  |  |  |  |
| 3RF24 05-.BB.. 3RF24 10-.BB.. 3RF24 12-.BB.. 3RF24 16-.BB.. | $\begin{aligned} & 5.2(4.5) \\ & 9.2 \\ & 12.5 \\ & 16 \end{aligned}$ | $\begin{aligned} & 4.6(4.0) \\ & 8.4 \\ & 11.5 \\ & 14 \end{aligned}$ | $\begin{aligned} & 4.2(3.5) \\ & 7.6 \\ & 10.5 \\ & 12.5 \end{aligned}$ | $\begin{aligned} & 10 \text { (8) } \\ & 16 \\ & 22 \\ & 28 \end{aligned}$ | 3RV1 021-1GA10 <br> 3RV1 021-1JA10 <br> 3RV1 021-1KA10 <br> 3RV1 021-4AA10 |  | $\begin{array}{r} 50 \\ 20 \\ 5 \\ 5 \end{array}$ |  |
| Order No. | Fused design with directly connected 3RB20 overload relay <br> Rated operational current $I_{\text {AC-53 }}$ acc. to IEC 60947-4-2 |  |  | Power loss at $I_{\text {AC-53 }}$ <br> at $40^{\circ} \mathrm{C}$ | Minimum load current | Max. leakage current | Rated impulse withstand capacity $I_{\text {tsm }}$ | $I^{2} t$ value |
|  | A | A | A | W | A | A | A | $A^{2} s$ |
| Main circuit |  |  |  |  |  |  |  |  |
| 3RF24 05-.BB. 4 3RF24 05-.BB. 6 3RF24 10-.BB.. 3RF24 12-.BB. 4 3RF24 12-.BB. 6 3RF24 16-.BB.. | $\begin{gathered} 4 \\ 7.8 \\ 9.5 \\ 11 \end{gathered}$ | $\begin{aligned} & 3.6 \\ & 7 \\ & 8.5 \\ & 10 \end{aligned}$ | $\begin{aligned} & 3.2 \\ & 6.2 \\ & 7.6 \\ & 9 \end{aligned}$ | $\begin{gathered} 7 \\ 13 \\ 16 \\ 18 \end{gathered}$ | $\begin{aligned} & 0.5 \\ & 0.5 \\ & 0.5 \\ & 0.5 \end{aligned}$ | $\begin{aligned} & 10 \\ & 10 \\ & 10 \\ & 10 \end{aligned}$ | $\begin{array}{r} 200 \\ 600 \\ 600 \\ 1200 \\ 1150 \\ 1150 \end{array}$ | $\begin{array}{r} 200 \\ 1800 \\ 1800 \\ 7200 \\ 6600 \\ 6600 \end{array}$ |
| Type |  |  | 3RF24 ..- |  |  | 3RF24 ..- |  |  |
| Main circuit |  |  |  |  |  |  |  |  |
| Controlled phas |  |  | Two-phas |  |  | Two-phas |  |  |
| Rated operation <br> - Operating rang <br> - Rated frequency | voltage $U_{e}$ |  | $\begin{aligned} & 48 \ldots 460 \\ & 40 \ldots 506 \\ & 50 / 60 \pm 10 \end{aligned}$ |  |  | 48 ... 600 <br> 40 ... 660 <br> $50 / 60 \pm 10$ |  |  |
| Rated insulation | oltage $U_{i}$ |  | 600 |  |  | 600 |  |  |
| Rated impulse w | stand volt | $\mathrm{J}_{\text {imp }}$ | 6 |  |  | 6 |  |  |
| Blocking voltage |  |  | 1200 |  |  | 1600 |  |  |
| Rage of voltage |  |  | 1000 |  |  | 1000 |  |  |
| Type |  |  | 3RF24 ..- |  |  | 3RF24 ..- |  |  |
| Control circui |  |  |  |  |  |  |  |  |
| Method of opera |  |  | DC opera |  |  | AC opera |  |  |
| Rated control su | ply voltage |  | 24 acc. to | 1131-2 |  | 110 ... 23 |  |  |
| Rated frequency of the control sup | y voltage |  | -- |  |  | $50 / 60 \pm 10$ |  |  |
| Control supply | tage, max. |  | 30 |  |  | 253 |  |  |
| Typical actuatin | current |  | 20 |  |  | 15 |  |  |
| Response voltag |  |  | 15 |  |  | 90 |  |  |
| Drop-out voltage |  |  | 5 |  |  | < 40 |  |  |
| Operating times <br> - ON-delay <br> - OFF-delay |  |  | $\begin{aligned} & 1 \\ & 1+\max . \end{aligned}$ | alf-wave |  | $\begin{aligned} & 5 \\ & 30+\max \end{aligned}$ | alf-wave |  |

1) The reduced values in brackets apply to a directly mounted circuit breaker and simultaneous butt-mounting

## Fused version with semiconductor protection (similar to type of coordination "2")1)

The semiconductor protection for the 3RF24 controls can be used with different protective devices. Siemens recommends the use of special SITOR semiconductor fuses. The table below lists the maximum permissible fuses for each 3RF24 control.

If a fuse is used with a higher rated current than specified, semiconductor protection is no longer guaranteed. However, smaller fuses with a lower rated current up to a lower rated current of the load can only be used after the behavior of the existing load alternation has been tested.

| Order No. | All-range fuses gR |  | Semiconductor fuses aR |  |  |  | Cable and line protection fuses |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | LV HRC design | Cylindrical design |  |  | LV HRC design | Cylindrical design |  |  |  |
|  | LV HRC design SITOR 3NE1 | Cylindr. design NEOZED 3SE1 ${ }^{2)}$ | $\begin{aligned} & \text { SITOR } \\ & \text { 3NE8 } \end{aligned}$ | $\begin{aligned} & 10 \mathrm{~mm} \\ & \times 38 \mathrm{~mm} \\ & \text { SITOR } \\ & \text { 3NC1 } \end{aligned}$ | $\begin{aligned} & 14 \mathrm{~mm} \\ & \times 51 \mathrm{~mm} \\ & \text { SITOR } \\ & \text { 3NC1 } \end{aligned}$ | $\begin{aligned} & 22 \mathrm{~mm} \\ & \times 58 \mathrm{~mm} \\ & \text { SITOR } \\ & \text { 3NC2 } \end{aligned}$ | $\begin{aligned} & \text { gG } \\ & \text { 3NA3 } \end{aligned}$ | $\begin{aligned} & 10 \mathrm{~mm} \\ & \times 38 \mathrm{~mm} \\ & \mathrm{gG} \\ & \text { 3NW6 } \end{aligned}$ | $\begin{aligned} & 14 \mathrm{~mm} \\ & \times 51 \mathrm{~mm} \\ & \mathrm{gG} \\ & \text { 3NW6 } \end{aligned}$ | $\begin{aligned} & 22 \mathrm{~mm} \\ & \times 58 \mathrm{~mm} \\ & \mathrm{gG} \\ & \text { 3NW6 } \end{aligned}$ | DIAZED <br> quick <br> 5SB1 |
| Operational voltage $\boldsymbol{U}_{\text {e }}$ up to 506 V |  |  |  |  |  |  |  |  |  |  |  |
| 3RF24 05-.BB. 4 | 3NE1 813-0 | 5SE1 320 | 3NE8 015-1 | 3NC1 020 | 3NC1 415 | 3NC2 220 | 3NA3 801-6 | 3NW6 001-1 | 3NW6 101-1 | -- | 5SB1 71 |
| 3RF24 10-.BB. 4 | 3NE1 802-0 | 5SE1 335 | 3NE8 020-1 | 3NC1 032 | 3NC1 450 | 3NC2 263 | 3NA3 805-6 | 3NW6 005-1 | 3NW6 105-1 | 3NW6 205-1 | 5SB3 11 |
| 3RF24 12-.BB. 4 | 3NE1 818-0 | 5SE1 363 | 3NE8 021-1 | 3NC1 032 | 3NC1 450 | 3NC2 280 | 3NA3 810-6 | 3NW6 010-1 | 3NW6 116-1 | 3NW6 210-1 | 5SB3 21 |
| 3RF24 16-.BB. 4 | 3NE1 818-0 | 5SE1 363 | 3NE8 022-1 | 3NC1 032 | 3NC1 450 | 3NC2 280 | 3NA3 812-6 | 3NW6 010-1 | 3NW6 116-1 | 3NW6 210-1 | 5SB3 22 |
| Operational voltage $U_{e}$ up to 660 V |  |  |  |  |  |  |  |  |  |  |  |
| 3RF24 05-.BB. 6 | 3NE1 813-0 | -- | 3NE8 015-1 | 3NC1 016 | 3NC1 420 | 3NC2 220 | 3NA3 801-6 | -- | -- | -- | -- |
| 3RF24 10-.BB. 6 | 3NE1 803-0 | -- | 3NE8 018-1 | 3NC1 032 | 3NC1 450 | 3NC2 250 | 3NA3 805-6 | -- | -- | -- | -- |
| 3RF24 12-.BB. 6 | 3NE1 817-0 | -- | 3NE8 021-1 | 3NC1 032 | 3NC1 450 | 3NC2 280 | 3NA3 810-6 | -- | -- | -- | -- |
| 3RF24 16-.BB. 6 | 3NE1 817-0 | -- | 3NE8 022-1 | 3NC1 032 | 3NC1 450 | 3NC2 280 | 3NA3 812-6 | -- | -- | -- | -- |

Suitable fuse holders, fuse bases and controls can be found in
Catalog LV 1, Chapter 19.

1) Type of coordination "2" according to EN 60947-4-1:

In the event of a short-circuit, the controls in the load feeder must not endanger persons or the installation. They must be suitable for further operation. For fused configurations, the protective device must be replaced.
2) For use only with operational voltage $U_{e}$ up to 400 V .

## Characteristic curves

Load diagram of motor


Operating data of motor
$I_{\mathrm{a}} \quad$ Direct starting current
$I_{\mathrm{e}}$ Rated operational current
$I_{\mathrm{b}}$ Operational current
$t_{\mathrm{a}} \quad$ Starting time
$t_{\mathrm{b}}$ Operating time
$t_{\mathrm{p}}$ Interval time
$t_{\text {OP }}$ ON period
$t_{\mathrm{s}}$ Operating cycle
$\mathrm{OP}[\%]=\frac{t_{\mathrm{OP}}}{t_{\mathrm{s}}} \times 100 \%$

## Solid-State Switching Devices for Switching Motors Solid-State Contactors

## 3RF24 solid-state contactors, three-phase

Maximum permissible switching frequency depending on the starting time $t_{\mathrm{a}}$ and the ON period $t_{\mathrm{OP}}$


For motors with a starting current of 4 to 7.2 times the rated current and with a full load (the dashed curves apply to the high currents during operation with motor starter protector)


For motors with a starting current of 4 to 7.2 times the rated current and with $60 \%$ load (the dashed curves apply to the high currents during operation with motor starter protector)

## Solid-State Switching Devices for Switching Motors <br> Solid-State Contactors

3RF24 solid-state contactors, three-phase


For motors with a starting current of up to 4 times the rated current and with a full load


For motors with a starting current of up to 4 times the rated current and with a $60 \%$ load

## Solid-State Switching Devices for Switching Motors

 Solid-State Contactors
## 3RF24 solid-state contactors, three-phase

## Dimensional drawings

Screw terminals


Spring-type terminals


Schematics

Two-phase controlled,
DC control supply voltage


Two-phase controlled,
AC control supply voltage


Sample schematic


## Overview

The integration of four conducting paths to a reverse switch, combined in one enclosure makes this device a particularly compact solution. Compared to conventional systems, for which two contactors are required, it is possible to save up to $50 \%$ width with the three-phase reversing contactors. Devices with 45 mm width cover motors up to 2.2 kW - and those with 90 mm width up to 3 kW .

Due to the integration into the SIRIUS modular system, it is possible to make a connection to a SIRIUS motor starter protector using a link module or with a 3RB20 solid-state overload relay without additional steps. It is possible to mount fuseless or fused motor feeders easily and quickly.

## Technical specifications

| Order No. |  | 3RF24 ..-1BD.. |
| :---: | :---: | :---: |
| General data |  |  |
| Ambient temperature |  |  |
| - During operation, derating from $40^{\circ} \mathrm{C}$ | ${ }^{\circ} \mathrm{C}$ | $-25 \ldots+60$ |
| - During storage | ${ }^{\circ} \mathrm{C}$ | $-55 \ldots+80$ |
| Installation altitude | m | 0 ... 1000; derating over 1000 m upon request |
| Shock resistance acc. to IEC 60068-2-27 | $\mathrm{g} / \mathrm{ms}$ | 15/11 |
| Vibration resistance acc. to IEC 60068-2-6 | $g$ | 2 |
| Degree of protection |  | IP20 |
| Insulation strength at $50 / 60 \mathrm{~Hz}$ (main/control circuit to floor) | V rms | 4000 |
| Electromagnetic compatibility (EMC) |  |  |
| - Emitted interference acc. to IEC 60947-4-3 <br> - Conducted interference voltage <br> - Emitted, high-frequency interference voltage |  | Class A for industrial applications ${ }^{1)}$ Class A for industrial applications |
| - Interference immunity |  |  |
| - Electrostatic discharge acc. to IEC 61000-4-2 (corresponds to degree of severity 3 ) | kV | Contact discharge 4; air discharge 8; behavior criterion 2 |
| - Induced RF fields acc. to IEC 61000-4-6 | MHz | 0.15 ... 80; $140 \mathrm{~dB} \mu \mathrm{~V}$; behavior criterion 1 |
| - Burst acc. to IEC 61000-4-4 | kV | 2/5 kHz; behavior criterion 1 |
| - Surge acc. to IEC 61000-4-5 ${ }^{\text {2) }}$ | kV | Conductor - ground 2; conductor - conductor 1; behavior criterion 2 |
| Connection type |  | (i) Screw terminals |
| Connection, main contacts |  |  |
| - Conductor cross-section |  |  |
| - Solid | $\mathrm{mm}^{2}$ | $2 \times(1.5 \ldots 2.5)^{3}, 2 \times(2.5 \ldots 6)^{3}$ |
| - Finely stranded with end sleeve | $\mathrm{mm}^{2}$ | $2 \times(1 \ldots 2.5)^{3}, 2 \times(2.5 \ldots 6)^{3}, 1 \times 10$ |
| - Finely stranded without end sleeve | $\mathrm{mm}^{2}$ | -- |
| - Solid or stranded, AWG cables |  | $2 \times$ (AWG $14 \ldots 10$ ) |
| - Stripped length | mm | 10 |
| - Terminal screw |  | M4 |
| - Tightening torque | Nm lb.in | $\begin{aligned} & 2 \ldots 2.5 \\ & 18 \ldots 22 \end{aligned}$ |

## Connection, auxiliary/control contacts

- Conductor cross-section
- With/without end sleeve

| mm | $1 \times(0.5 \ldots 2.5), 2 \times(0.5 \ldots 1.0)$ |
| :--- | :--- |
| AWG $A W G 20 \ldots 12$ |  |

- Stripped length
mm 7
- Terminal screw M3
- Tightening torque, ( $\varnothing$ 3.5, PZ 1)
Nm $\quad 0.5 \ldots 0.6$
lb.in $\quad 4.5 \ldots 5.3$


## Permissible mounting positions



1) These products were built as Class A devices. The use of these devices in residential areas could result in lead in radio interference. In this case these may be required to introduce additional interference suppression measures
2) To maintain the values, a 3 TX7 462-3L surge suppressor (see Catalog LV 1, Chapter 3, page 3/119) should be used between the phases L1 and L3 as close as possible to the switchgear.
3) If two different conductor cross-sections are connected to one clamping point, both cross-sections must lie in the range specified. If identical cross-sections are used, this restriction does not apply.

## Solid-State Switching Devices for Switching Motors

## Solid-State Contactors

## 3RF24 solid-state reversing contactors,

three-phase

| Order No. | Fuseless design with motor starter protector CLASS 10 |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Rated operational current $I_{\text {AC-53 }}{ }^{1)}$ acc. to IEC 60947-4-2 |  |  | Power loss at $I_{\text {AC-53 }}$ <br> at $40^{\circ} \mathrm{C}$ | Short-circuit protection with type of coordination "1" at an operational voltage of $U_{\mathrm{e}}$ to 440 V |  |  |  |
|  | at $40{ }^{\circ} \mathrm{C}$ | UL/CSA, at $50^{\circ} \mathrm{C}$ | at $60^{\circ} \mathrm{C}$ |  | Motor starter pros | tector | $I_{\text {q }}$ |  |
|  | A | A | A | W | Type |  | kA |  |
| Main circuit |  |  |  |  |  |  |  |  |
| 3RF24 03-.BD. 4 3RF24 05-.BD. 4 3RF24 10-.BD. 4 | $\begin{aligned} & 3.8(3.4) \\ & 5.4(4.8) \\ & 7.4 \end{aligned}$ | $\begin{aligned} & 3.5(3.1) \\ & 5 \quad(4.3) \\ & 6.8 \end{aligned}$ | $\begin{aligned} & 3.2(2.8) \\ & 4.6 \text { (3.8) } \\ & 6.2 \end{aligned}$ | $\begin{gathered} 7(6) \\ 9(8) \\ 13 \end{gathered}$ | 3RV1 021-1FA10 3RV1 021-1GA10 3RV1 021-1JA10 |  | $\begin{aligned} & 50 \\ & 50 \\ & 10 \end{aligned}$ |  |
| Order No. | Fused design with directly connected 3RB20 overload relay |  |  |  | Minimum load current | Max. leakage current | Rated impulse withstand capacity $I_{\text {tsm }}$ | $I^{2} t$ value |
|  | Rated operational current $I_{\text {AC-53 }}$ acc. to IEC 60947-4-2 |  |  | Power loss at $I_{\text {AC-53 }}$ |  |  |  |  |
|  | at $40^{\circ} \mathrm{C}$ | $\begin{aligned} & \text { UL/CSA, } \\ & \text { at } 50^{\circ} \text { º } \end{aligned}$ | at $60^{\circ} \mathrm{C}$ | at $40^{\circ} \mathrm{C}$ |  |  |  |  |
|  | A | A | A | W | A | mA | A | $A^{2} s$ |
| Main circuit |  |  |  |  |  |  |  |  |
| 3RF24 03-.BD. 4 3RF24 05-.BD. 4 3RF24 10-.BD. 4 | $\begin{aligned} & 3.8 \\ & 5.4 \\ & 7.4 \end{aligned}$ | $\begin{aligned} & 3.5 \\ & 5 \\ & 6.8 \end{aligned}$ | $\begin{aligned} & 3.2 \\ & 4.6 \\ & 6.2 \end{aligned}$ | $\begin{array}{r} 6 \\ 8 \\ 16 \end{array}$ | $\begin{aligned} & 0.5 \\ & 0.5 \\ & 0.5 \end{aligned}$ | $\begin{aligned} & 10 \\ & 10 \\ & 10 \end{aligned}$ | $\begin{aligned} & 200 \\ & 600 \\ & 600 \end{aligned}$ | $\begin{array}{r} 200 \\ 1800 \\ 1800 \end{array}$ |


| Type |  | 3RF24 ..-.BD. 4 |  |
| :---: | :---: | :---: | :---: |
| Main circuit |  |  |  |
| Controlled phases |  | Two-phase |  |
| Rated operational voltage $\boldsymbol{U}_{\mathbf{e}}{ }^{2)}$ | V | 48 ... 460 |  |
| - Operating range | V | $40 \ldots 506$ |  |
| - Rated frequency | Hz | 50/60 $\pm 10$ \% |  |
| Rated insulation voltage $\boldsymbol{U}_{\mathrm{i}}$ | V | 600 |  |
| Rated impulse withstand voltage $\boldsymbol{U}_{\text {imp }}$ | kV | 6 |  |
| Blocking voltage | V | 1200 |  |
| Rage of voltage rise | V/ $/$ s | 1000 |  |
| Type |  | 3RF24 ..-.BDO. | 3RF24 ..-.BD2. |
| Control circuit |  |  |  |
| Method of operation |  | DC operation | AC operation |
| Rated control supply voltage $\boldsymbol{U}_{\mathbf{s}}$ | V | 24 acc. to EN 61131-2 | $110 \ldots 230$ |
| Rated frequency of the control supply voltage | Hz | -- | 50/60 $\pm 10$ \% |
| Control supply voltage, maximum | V | 30 | 253 |
| Typical actuating current | mA | 15 | 10 |
| Response voltage | V | 15 | 90 |
| Drop-out voltage | V | 5 | < 40 |
| Operating times <br> - ON-delay <br> - OFF-delay <br> - Interlocking time | $\begin{aligned} & \mathrm{ms} \\ & \mathrm{~ms} \\ & \mathrm{~ms} \end{aligned}$ | $\begin{aligned} & 5 \\ & 5+\text { max. one half-wave } \\ & 60 \text {... } 100 \end{aligned}$ | $\begin{aligned} & 20 \\ & 10+\text { max. one half-wave } \\ & 50 \ldots 100 \end{aligned}$ |

1) The reduced values in brackets apply to a directly mounted circuit breaker and simultaneous butt-mounting.
2) To reduce the risk of a phase short circuit due to overvoltage, we recommend using a varistor type 3TX7 462-3L between the phases L1 and L3 and as close as possible to the switchgear. We recommend a design with semiconductor protection as short-circuit protection.

## Fused version with semiconductor protection (similar to type of coordination "2")1)

The semiconductor protection for the 3RF24 controls can be used with different protective devices. Siemens recommends the use of special SITOR semiconductor fuses. The table below lists the maximum permissible fuses for each 3RF24 control.

If a fuse is used with a higher rated current than specified, semiconductor protection is no longer guaranteed. However, smaller fuses with a lower rated current up to a lower rated current of the load can only be used after the behavior of the existing load alternation has been tested.

| Order No. | All-range fuses gR |  | Semiconductor fuses aR |  |  |  | Cable and line protection fuses |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | LV HRC design | Cylindrical design |  |  | LV HRC design | Cylindrical design |  |  |
|  | LV HRC design SITOR 3NE1 | Cylindr. design NEOZED 3SE1 ${ }^{2}$ | SITOR 3NE8 | $\begin{aligned} & 10 \mathrm{~mm} \\ & \times 38 \mathrm{~mm} \\ & \text { SITOR } \\ & \text { 3NC1 } \end{aligned}$ | $\begin{aligned} & 14 \mathrm{~mm} \\ & \times 51 \mathrm{~mm} \\ & \text { SITOR } \\ & \text { 3NC1 } \end{aligned}$ | $\begin{aligned} & 22 \mathrm{~mm} \\ & \times 58 \mathrm{~mm} \\ & \text { SITOR } \\ & \text { 3NC2 } \end{aligned}$ | gG <br> 3NA3 | $\begin{aligned} & 10 \mathrm{~mm} \\ & \times 38 \mathrm{~mm} \\ & \mathrm{gG} \\ & \text { 3NW6 } \end{aligned}$ | $\begin{aligned} & 14 \mathrm{~mm} \\ & \times 51 \mathrm{~mm} \\ & \mathrm{gG} \\ & \text { 3NW6 } \end{aligned}$ | DIAZED <br> quick <br> 5SB1 |
| Operational voltage $\boldsymbol{U}_{\text {e }}$ up to 506 V |  |  |  |  |  |  |  |  |  |  |
| 3RF24 03-.BD.. | 3NE1 813-0 | 5SE1 335 | 3NE8 015-1 | 3NC1 020 | 3NC1 415 | 3NC2 220 | 3NA3 801-6 | 3NW6 001-1 | 3NW6 101-1 | 5SB1 71 |
| 3RF24 05-.BD.. | 3NE1 802-0 | 5SE1 335 | 3NE8 020-1 | 3NC1 032 | 3NC1 450 | 3NC2 263 | 3NA3 805-6 | -- | -- | 5SB3 11 |
| 3RF24 10-.BD.. | 3NE1 802-0 | 5SE1 335 | 3NE8 020-1 | 3NC1 032 | 3NC1 450 | 3NC2 263 | 3NA3 805-6 | -- | -- | 5SB3 11 |

Suitable fuse holders, fuse bases and controls can be found in
Catalog LV 1, Chapter 19.

1) Type of coordination "2" according to EN 60947-4-1:

In the event of a short-circuit, the controls in the load feeder must not endanger persons or the installation. They must be suitable for further operation. For fused configurations, the protective device must be replaced.
2) For use only with operational voltage $U_{e}$ up to 400 V .

## Characteristic curves

Load diagram of motor


## Solid-State Switching Devices for Switching Motors Solid-State Contactors

3RF24 solid-state reversing contactors, three-phase

Maximum permissible switching frequency depending on the starting time $t_{\mathrm{a}}$ and the ON period $t_{\mathrm{OP}}$


For motors with a starting current of 4 to 7.2 times the rated current and with a full load


For motors with a starting current of 4 to 7.2 times the rated current and with a $60 \%$ load

# Solid-State Switching Devices for Switching Motors <br> Solid-State Contactors 



For motors with a starting current of up to 4 times the rated current and with a full load


For motors with a starting current of up to 4 times the rated current and with a $60 \%$ load

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## Dimensional drawings

Screw terminals


## Schematics

Two-phase controlled,
DC control supply voltage


Two-phase controlled,
AC control supply voltage


Sample schematic


## Get more information

Low-Voltage Controls and Distribution www.siemens.com/lowvoltage

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| :--- | :--- |
| Industry Sector |  |
| Low Voltage Controls and Distribution |  |
| Postfach 4848 |  |
| 90026 NÜRNBERG | © Siemens AG 2009 |
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| WWW.siemens.com/automation |  |


[^0]:    1) Applies to the version "Low Power" 3RF21 ..-.AA...-OKNO.
[^1]:    1) Only "Extended" load monitoring.
